

# PhD. Defense

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## Theory of Sequences Tailored for Program Verification

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Théorie des séquences adaptée à la vérification des programmes

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by **Hichem Rami AIT EL HARA**<sup>1,2</sup>

Under the supervision of **François BOBOT**<sup>2</sup> and **Guillaume BURY**<sup>1</sup>

<sup>1</sup>OCamlPro

<sup>2</sup>Université Paris-Saclay, CEA, LIST



# Software is everywhere

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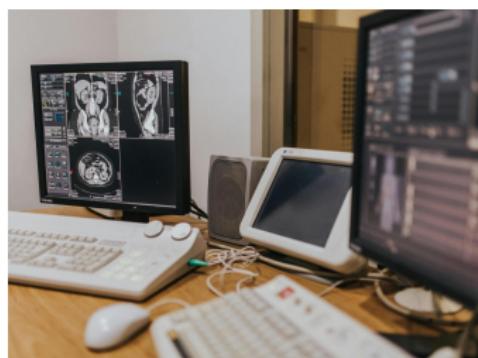
Personal information



Energy



Aerospace

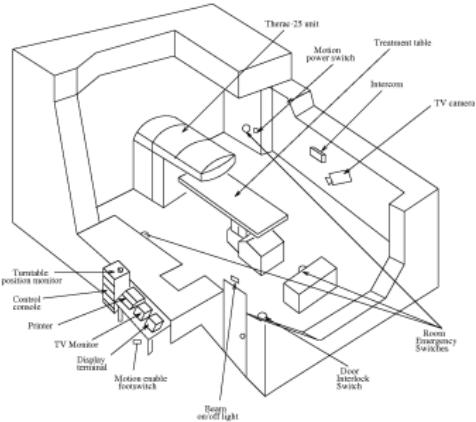


Healthcare

# And it can be faulty (bugged)



Ariane 5 \*  
(Arithmetic overflow)  
**Loss of over US\$370 million**



Therac-25 \*\*  
(Race condition)  
**Deaths and injuries of patients**

More examples:

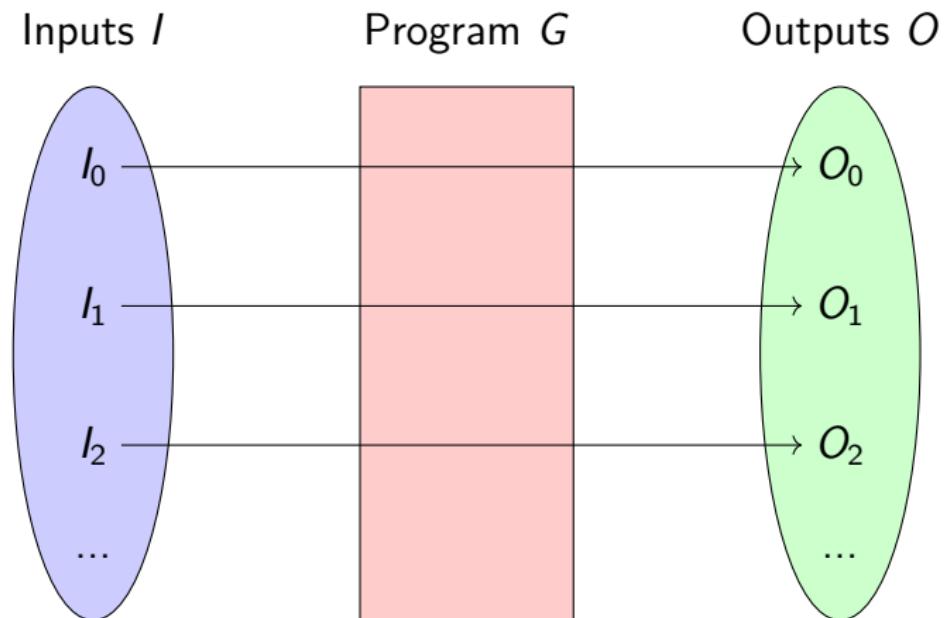
[https://en.wikipedia.org/wiki/List\\_of\\_software\\_bugs](https://en.wikipedia.org/wiki/List_of_software_bugs)

\*Photo: ©ESA

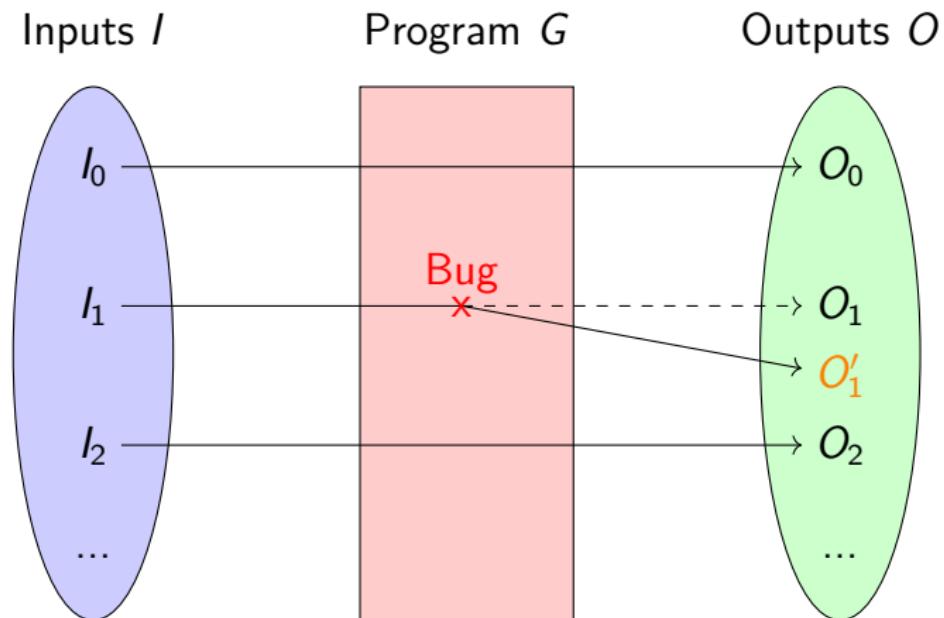
\*\*Figure from: "Medical Devices: The Therac-25" by Nancy G. Leveson

Behind the software, there are programs.

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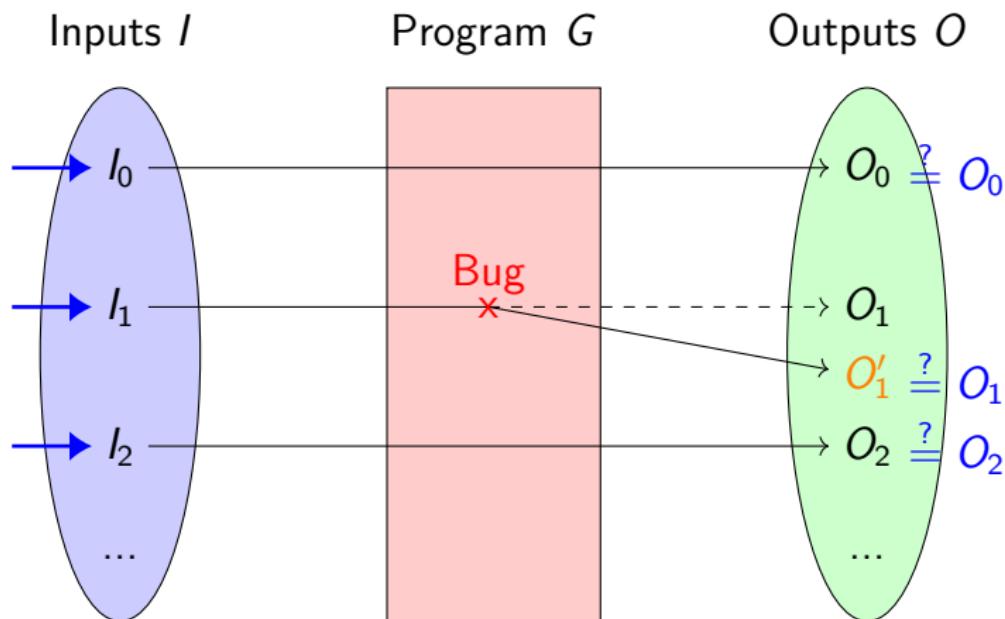


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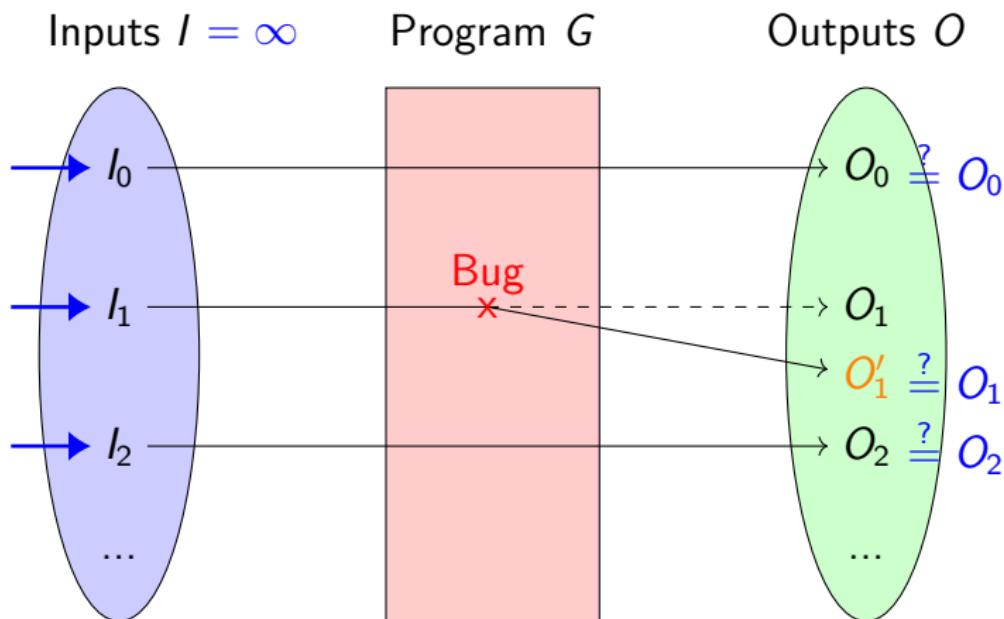
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## Testing



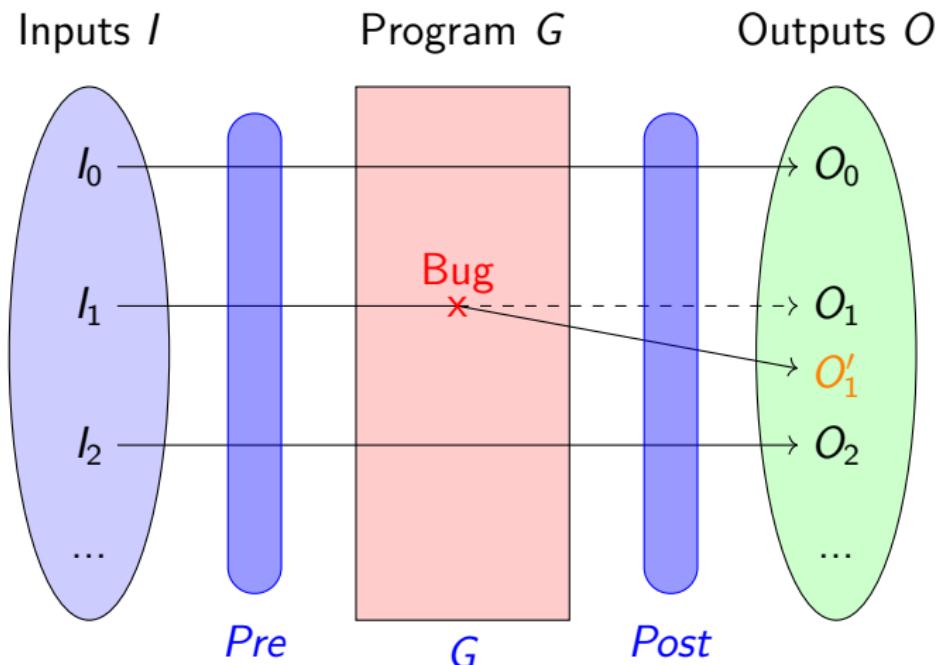
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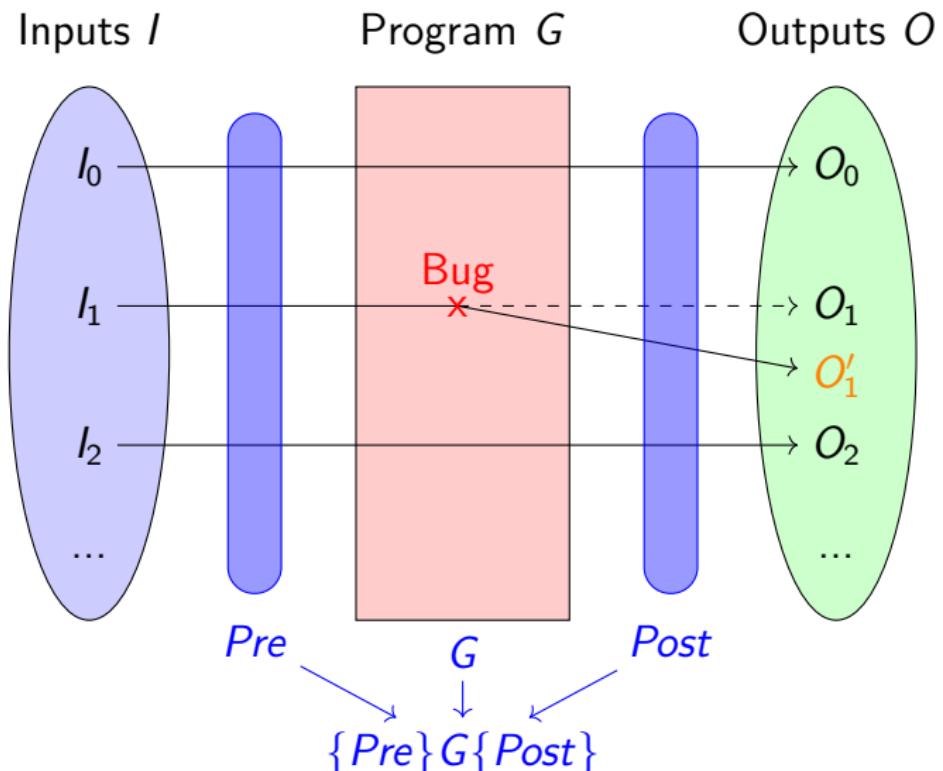
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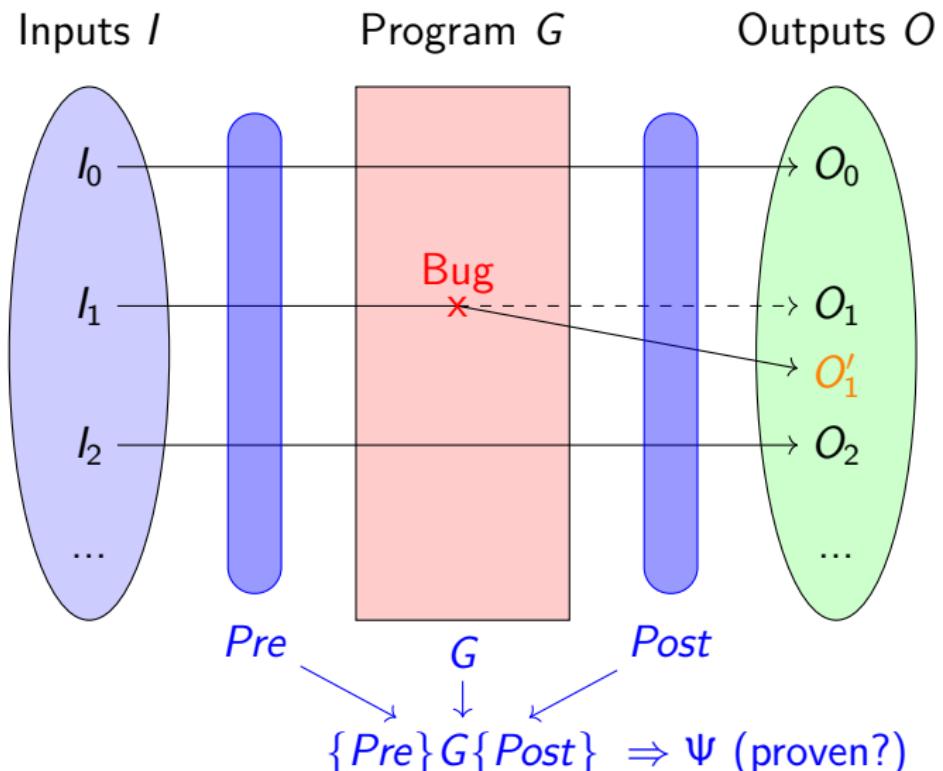
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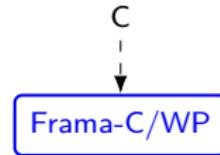


# Avoiding Bugs in the Real World

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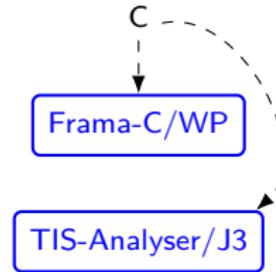
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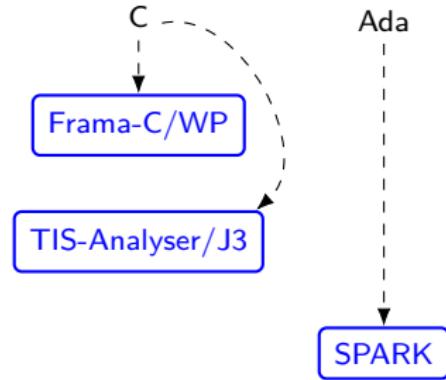
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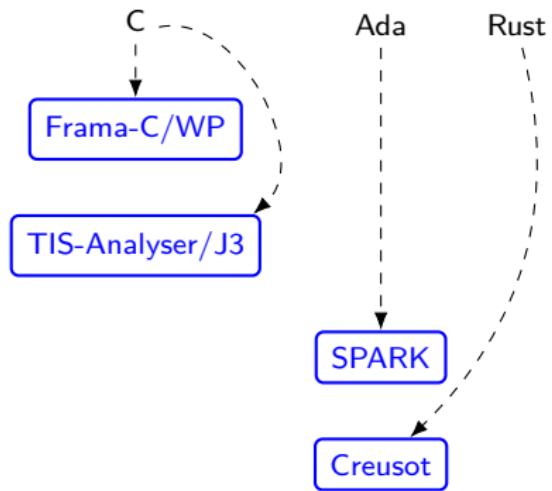
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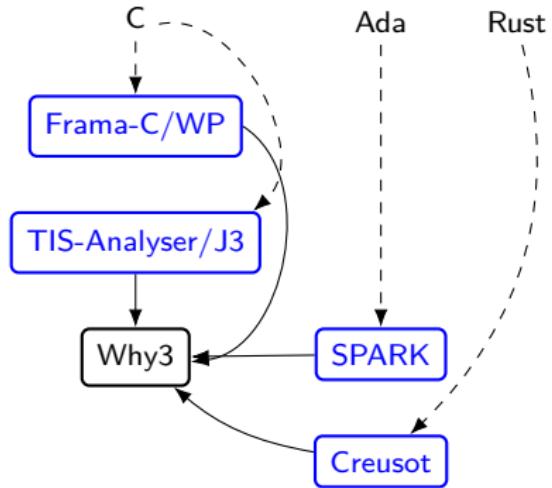


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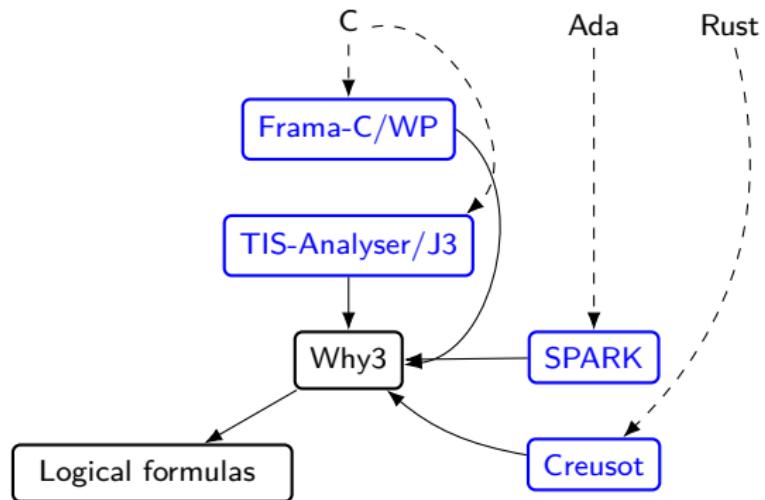
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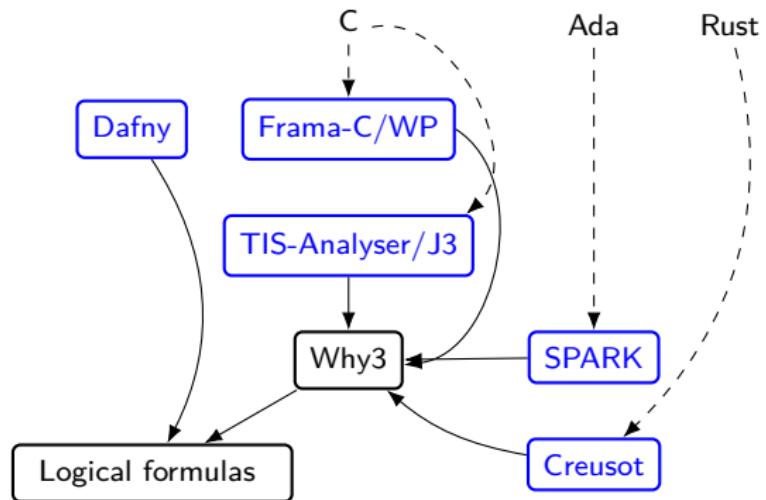
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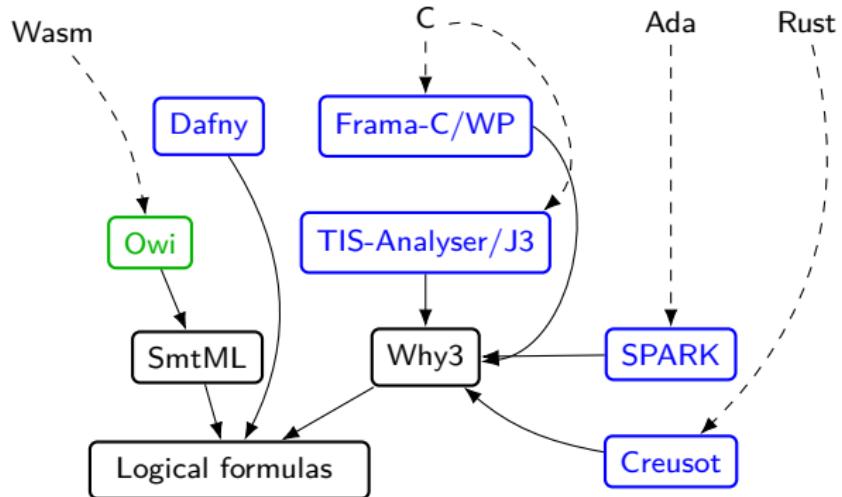
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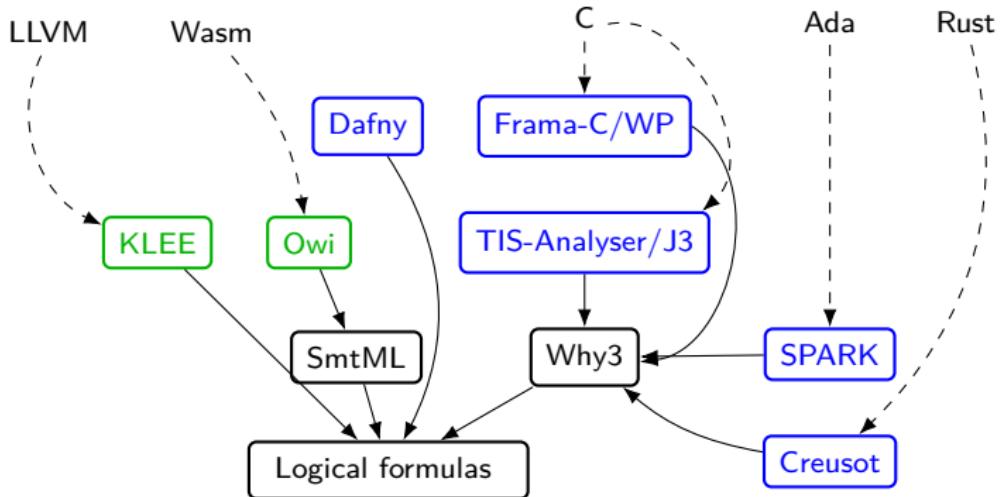
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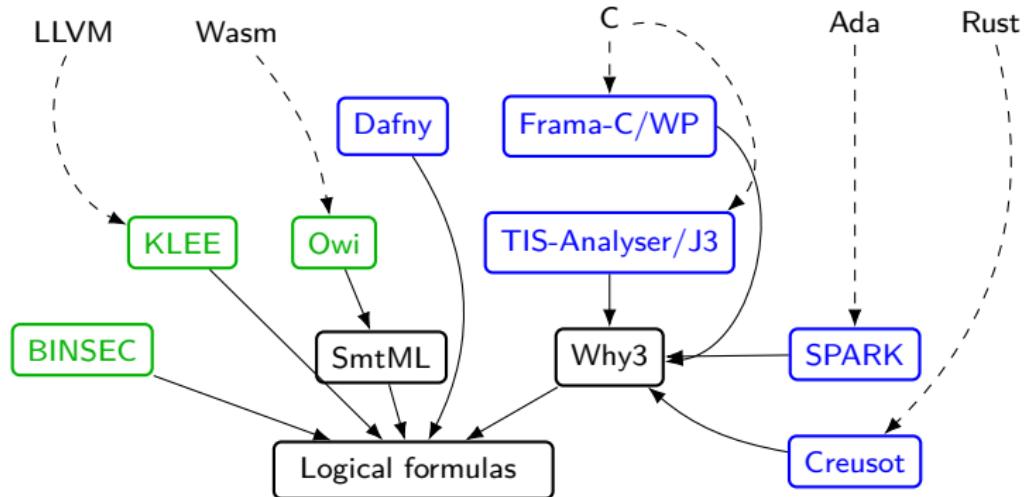
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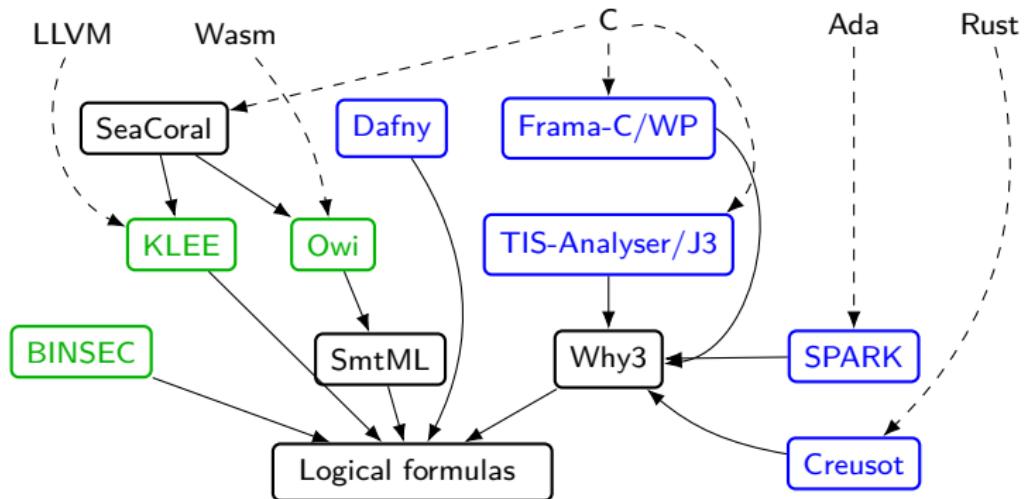
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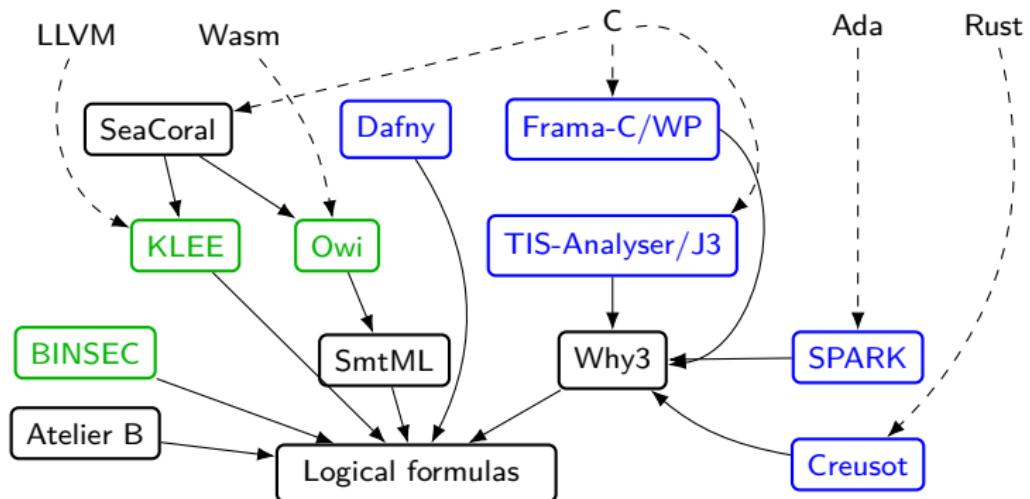
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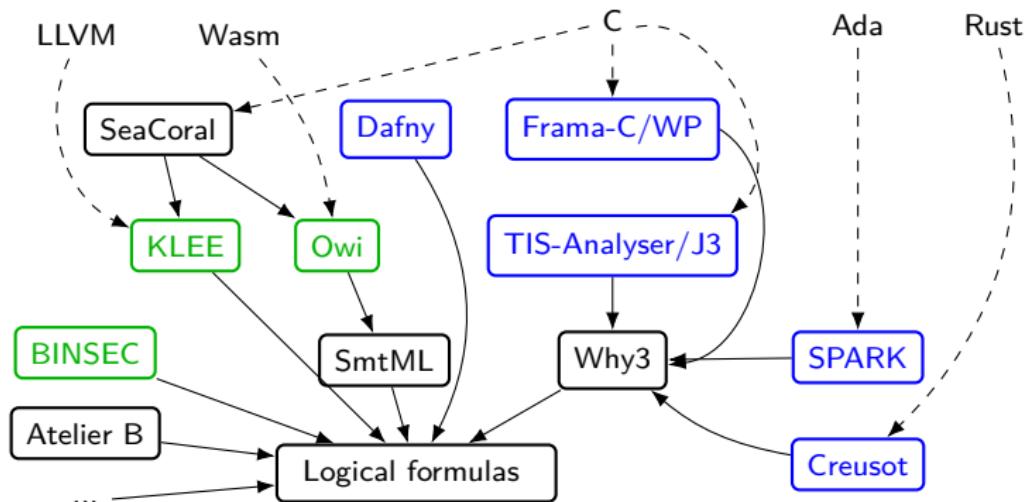
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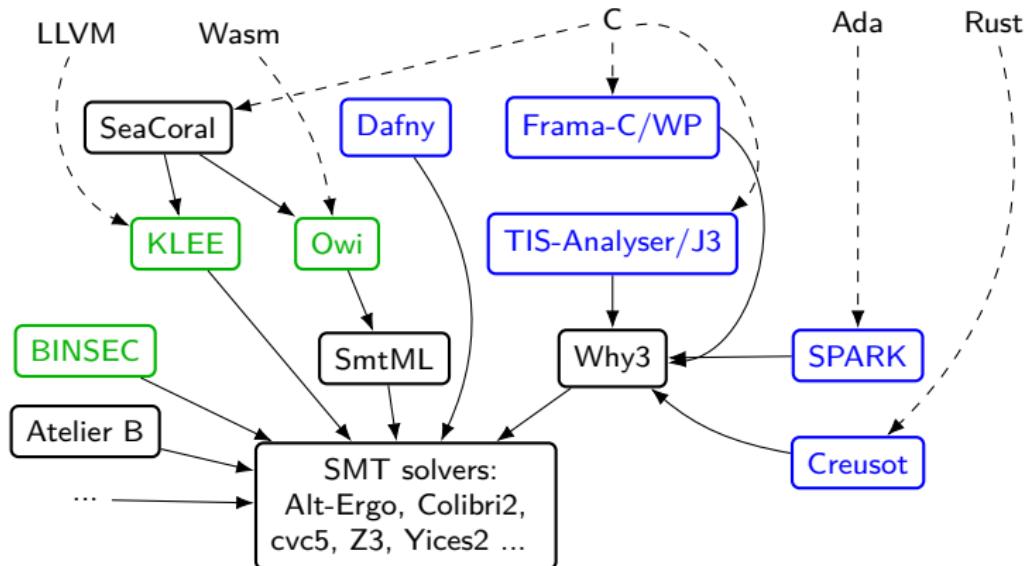
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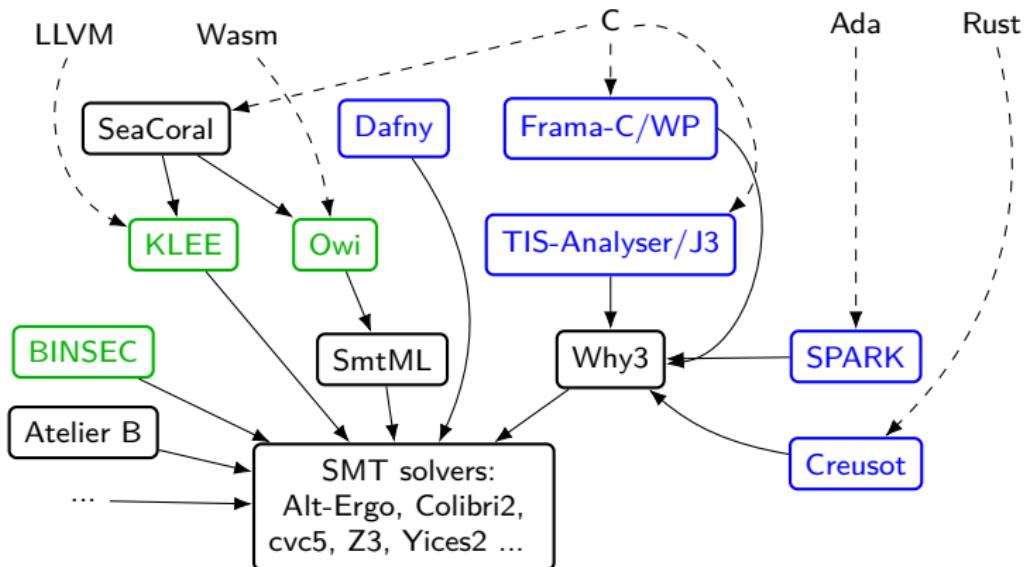
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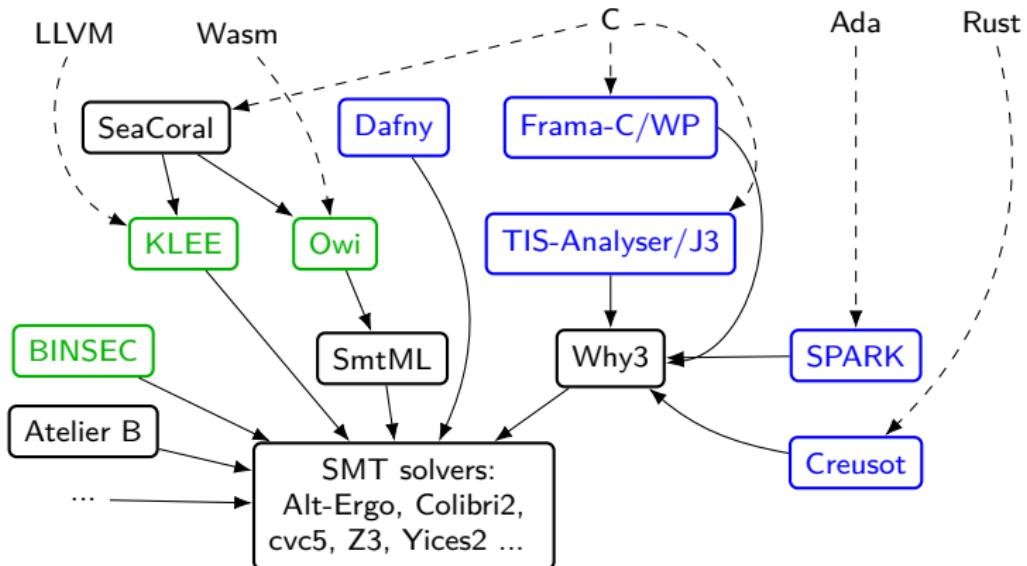


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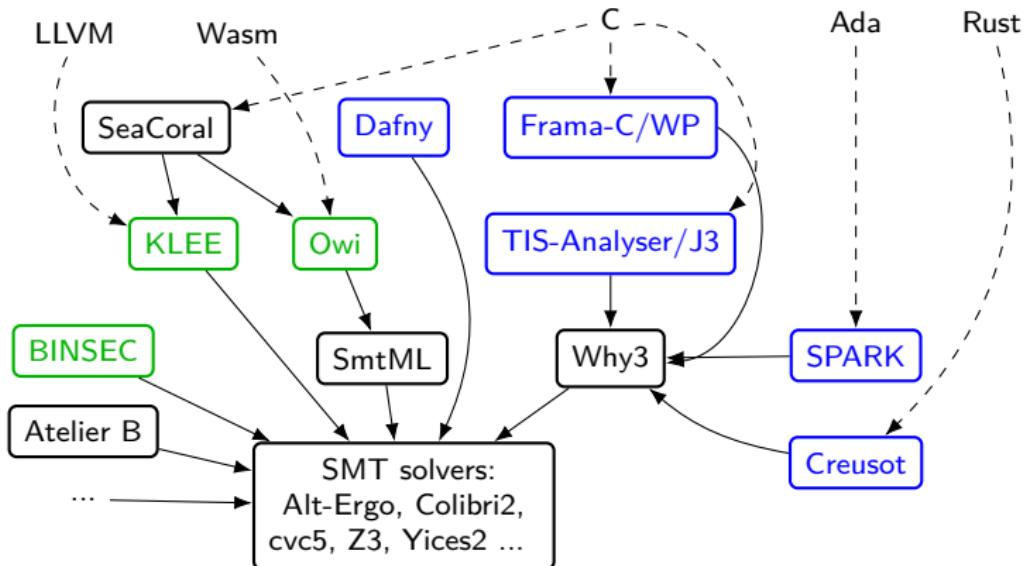
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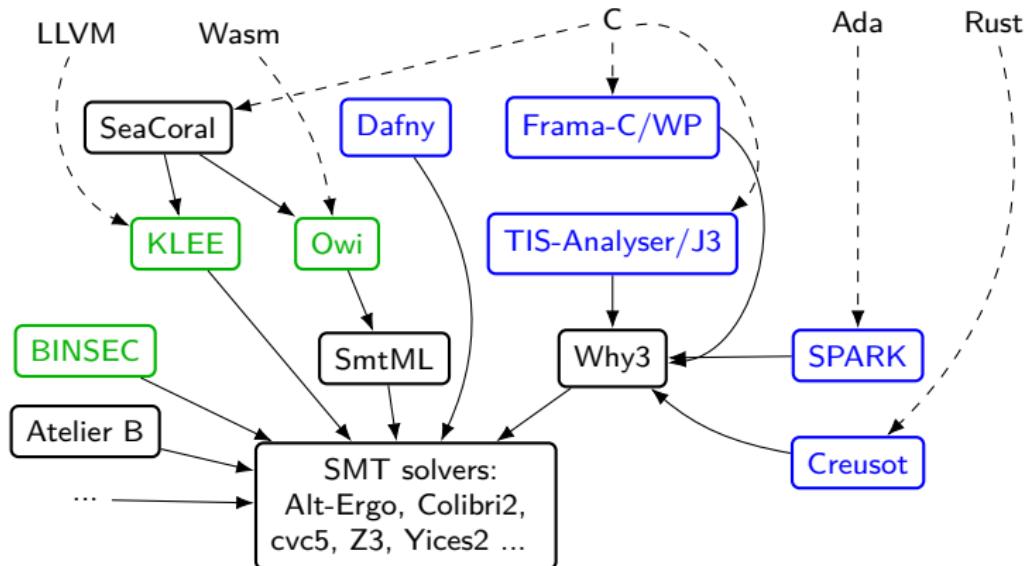
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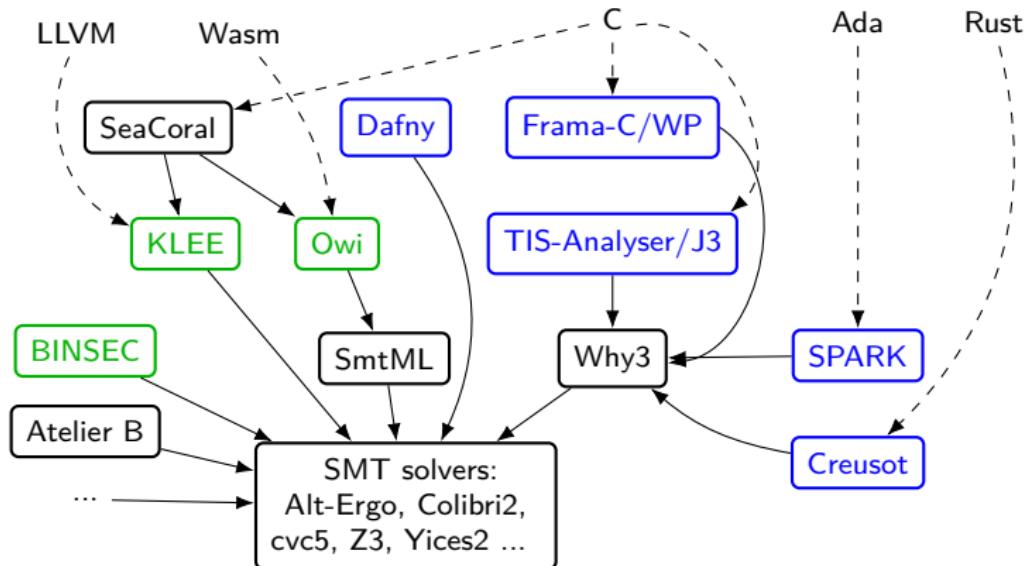
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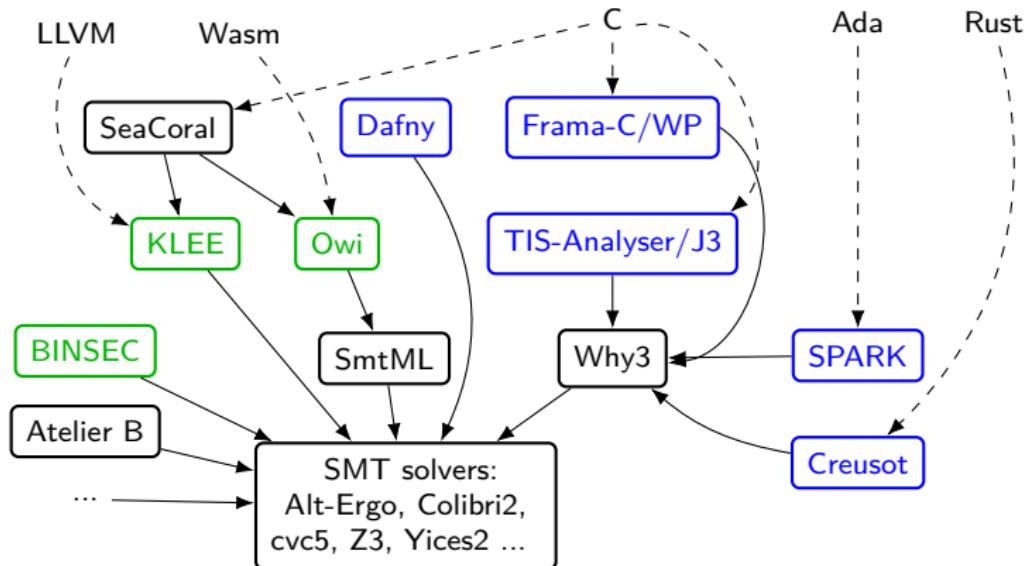
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# What is SMT (Satisfiability Modulo Theories)?

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## Definition

Boolean Satisfiability (Propositional Logic)

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Built-in First-Order Logic Theories

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No, therefore  $F$  is **unsatisfiable**. Inversely  $\neg F$  is **valid**.

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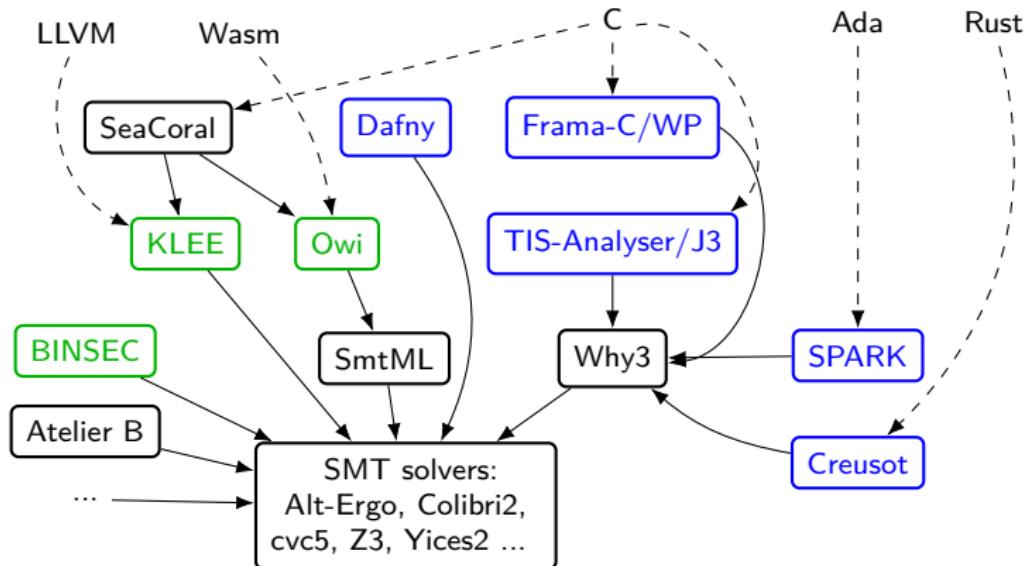
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# Avoiding Bugs in the Real World



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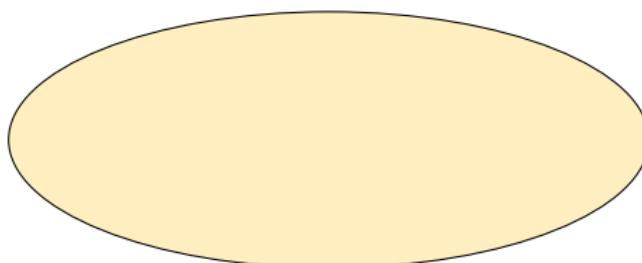
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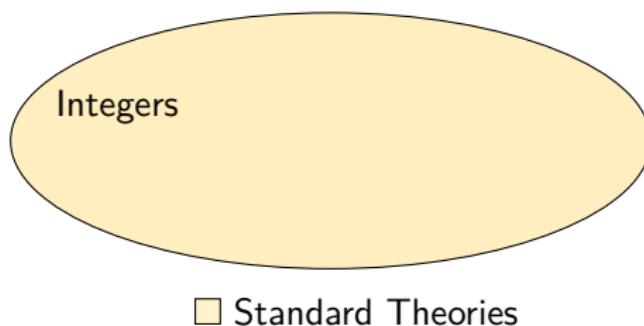


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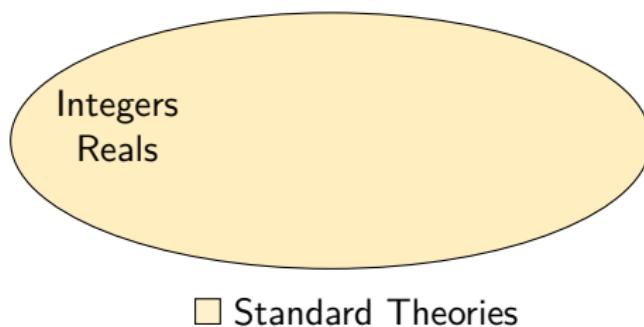
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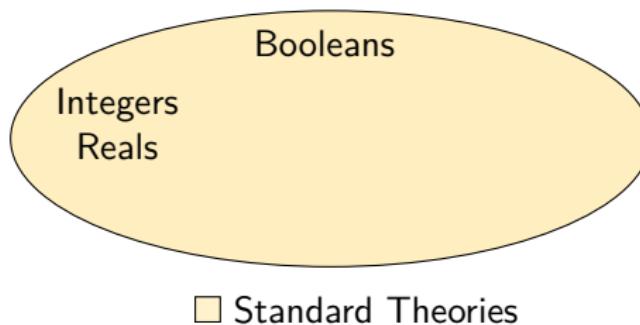
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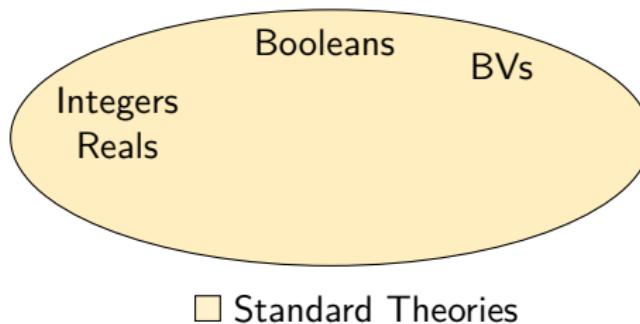
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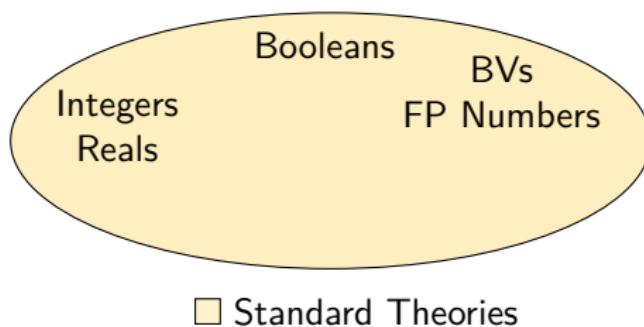
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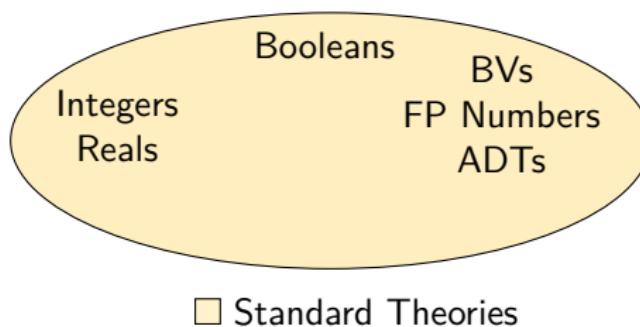
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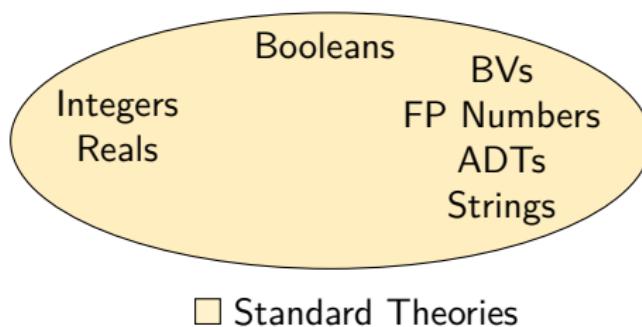
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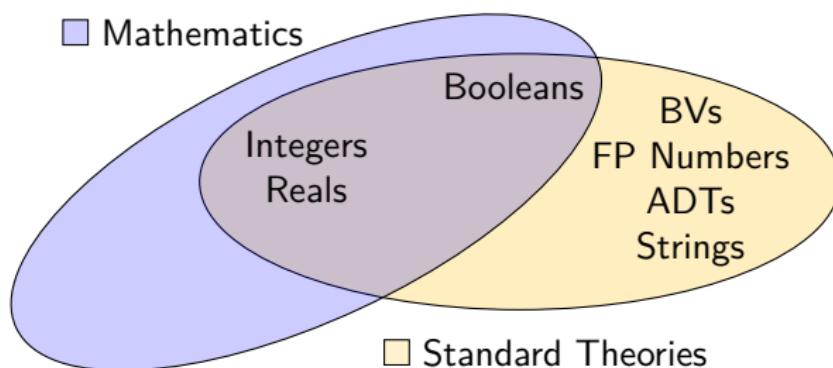
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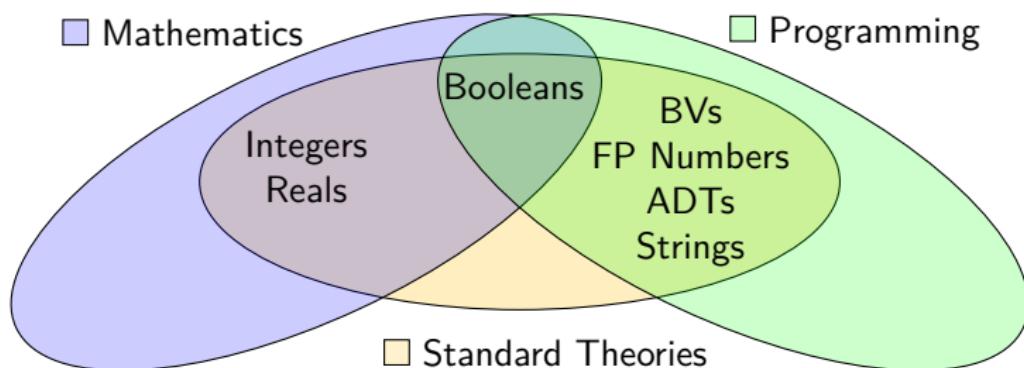
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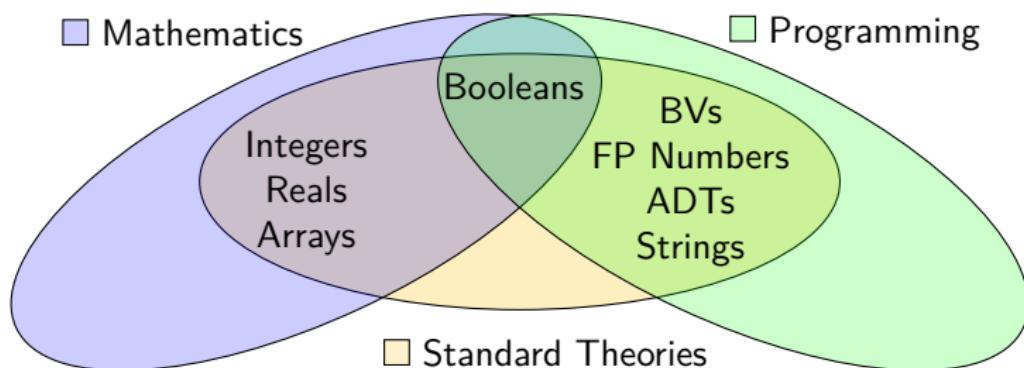
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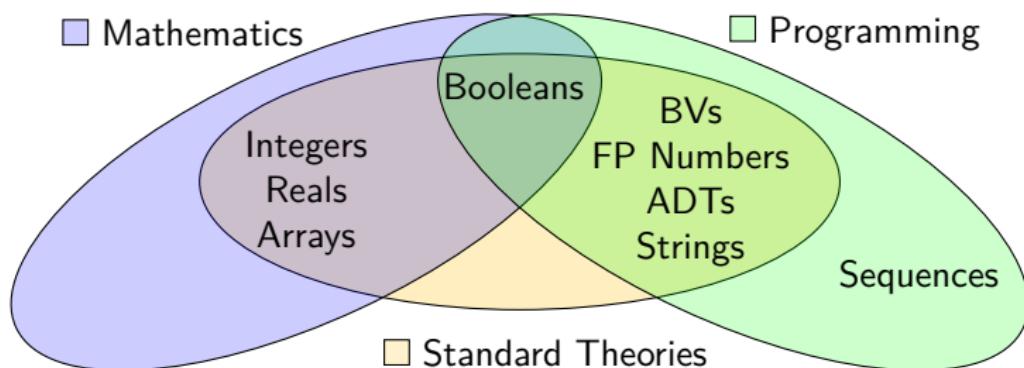
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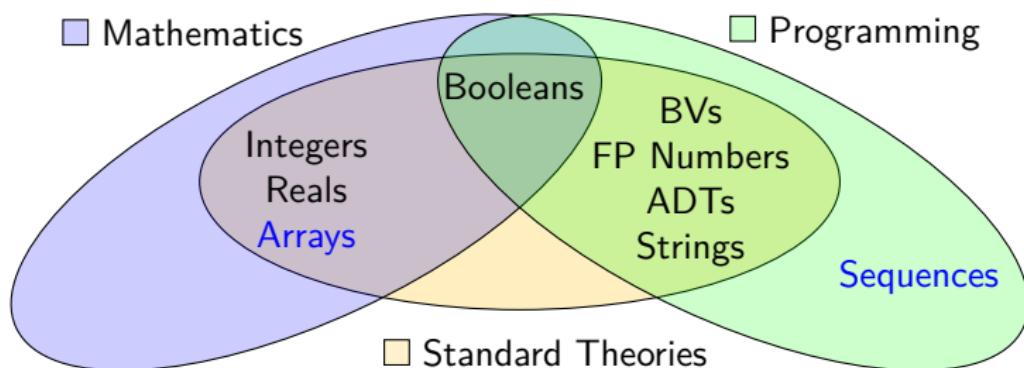
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Sequences are more suitable as they are semantically closer.

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An  $n$ -indexed sequence (or  $n$ -sequence)  $s$  is a sequence that is indexed from a first index  $f_s$  to a last index  $l_s$ .

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# Outline

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## Empty n-indexed sequence

An n-indexed sequence  $s$  is said to be empty if  $l_s < f_s$ . Two empty n-indexed sequences  $a$  and  $b$  are equal only if  $f_a = f_b$  and  $l_a = l_b$ .

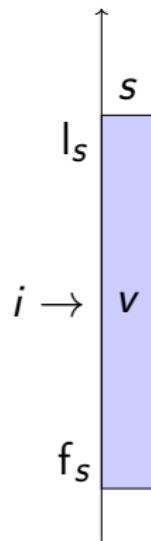
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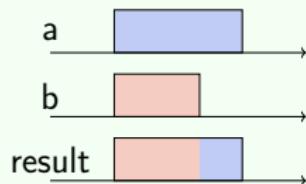
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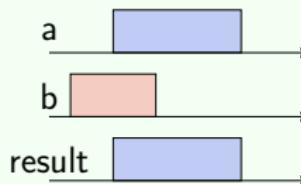
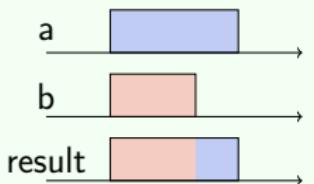
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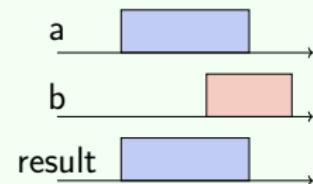
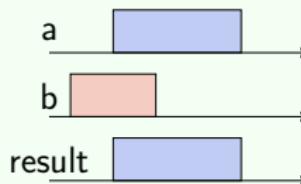
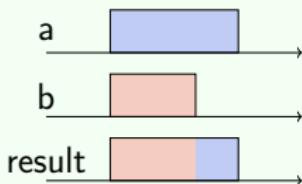
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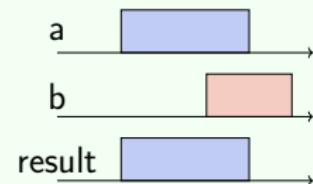
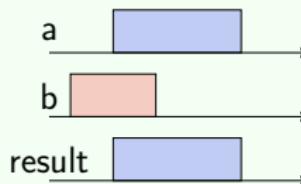
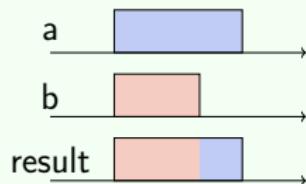
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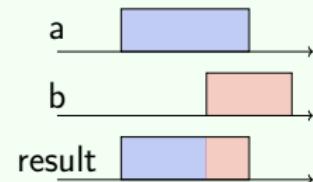
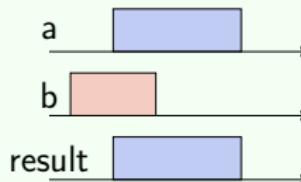
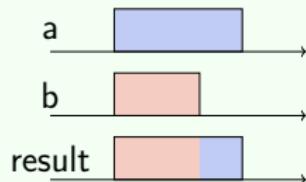
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## Example



In the theory of sequences (in cvc5)  $\text{update}(a, i, b)$ :



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To read more on SMT theory design and semantic choices:

- ▶ **"On SMT Theory Design: The Case of Sequences"**  
Hichem Rami Ait-El-Hara, François Bobot and Guillaume Bury. [LPAR 2024](#)

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### Extensionality

The theory of n-indexed sequences is extensional. Therefore, given two n-indexed sequences  $a$  and  $b$ :

$$\begin{aligned}(a = b) \equiv \\ (f_a = f_b \wedge l_a = l_b \wedge \\ \forall i : \text{Int}, f_a \leq i \leq l_a \rightarrow \text{get}(a, i) = \text{get}(b, i))\end{aligned}$$

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# Axiomatization/Encoding of n-Sequences

---

Axiomatization (with arrays):

- ▶ Most operations need to be axiomatized.
- ▶ Introduces too many quantified formulas.

Encoding using Sequences and Algebraic Data Types:

- ▶ Avoids using as many quantifiers.
- ▶ Depends on two other theories (Sequences and ADTs).
- ▶ Differences in the semantics make the definitions complex.

# Reasoning with Sequences and Algebraic Data Types I

---

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- ▶  $f_n = n.\text{fst}$  and  $l_n = n.\text{fst} + \text{len}(n.\text{seq}) - 1$
- ▶  $\text{get}(n, i) = \text{nth}(n.\text{seq}, i - n.\text{fst})$

Except  $\text{const}(f, l, v)$ , which has **no counterpart** in the theory of sequences:

# Reasoning with Sequences and Algebraic Data Types I

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n-Indexed sequences are defined as a record:

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Except  $\text{const}(f, l, v)$ , which has **no counterpart** in the theory of sequences:

- ▶ It can be axiomatized:

$$\begin{aligned} n = \text{const}(f, l, v) \iff & f_n = f \wedge l_n = l \wedge \\ & \forall i. f \leq i \leq l \implies \text{get}(n, i) = v \end{aligned}$$

# Outline

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## 1. The SMT theory of n-Indexed Sequences

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- Using existing theories
- **Porting calculi on Sequences to n-Sequences**
- The Shared-Slices calculus
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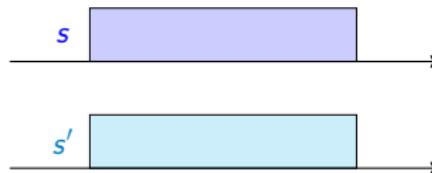
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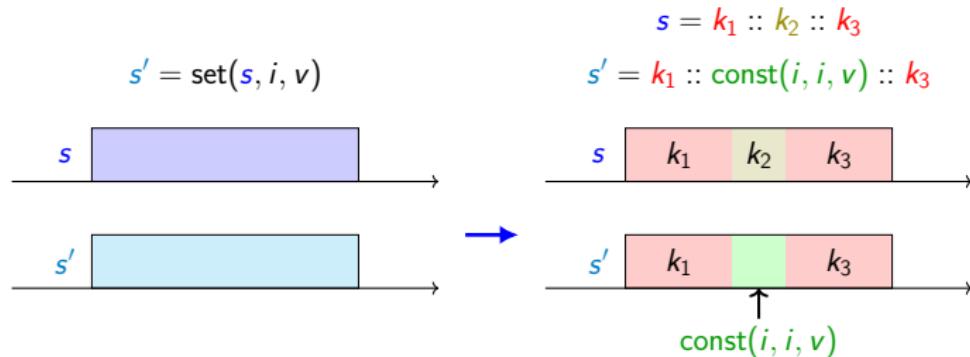
$$s' = \text{set}(s, i, v)$$



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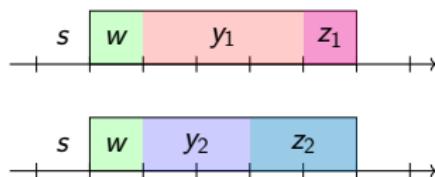
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$$s = \textcolor{green}{w} :: \textcolor{red}{y_1} :: \textcolor{violet}{z_1}$$

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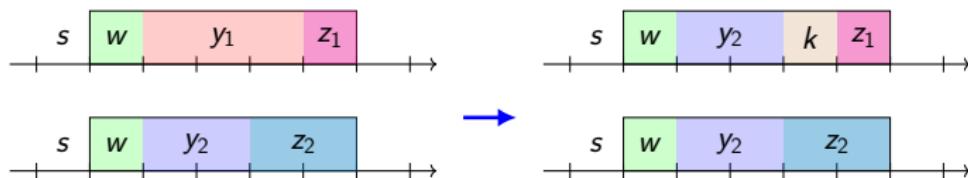
- ▶ **BASE:** based on string reasoning, works by reducing to concatenations.

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To read more on NS-BASE and NS-EXT:

- ▶ **"An SMT Theory for n-Indexed Sequences"**  
Hichem Rami Ait-El-Hara, François Bobot, and Guillaume Bury. [SMT 2024](#)
- ▶ **"Reasoning over n-indexed sequences in SMT"**  
Hichem Rami Ait-El-Hara, François Bobot, and Guillaume Bury. [Acta Informatica 62.3 \(Aug. 2025\)](#)

# Calculus Summary: NS-BASE and NS-EXT

---

Operations	NS-BASE	NS-EXT
get set	String reasoning	Array reasoning
concat slice update ...	String reasoning	String reasoning

Limitations:

- ▶ Eager normalization is often costly and sometimes unnecessary.

Alternative:

- ▶ A new calculus that lazily reasons over slices.

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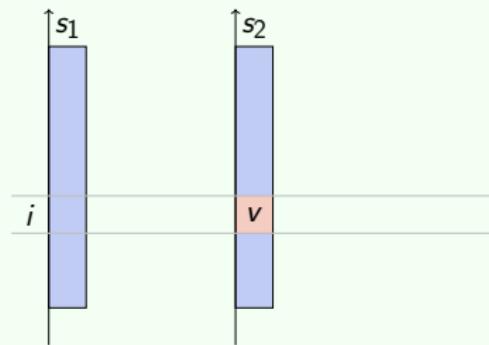
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## Illustration



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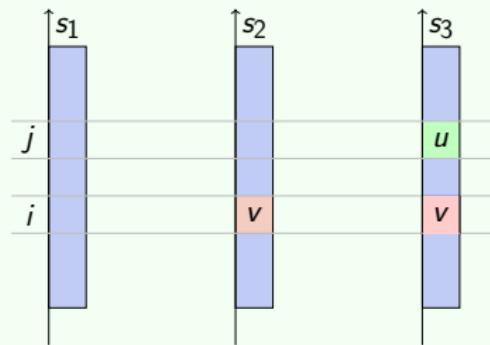
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## Illustration

Given  $s_3 = \text{set}(s_2, j, u)$ ,  
With  $f_{s_2} \leq j \leq l_{s_2}$ :

- ▶  $f_{s_2} = f_{s_3} \wedge l_{s_2} = l_{s_3}$
- ▶  $s_1 \xleftrightarrow{\{i,j\}} s_3$



## The Shared-Slices (NS-ShS) Calculus II

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Slice-ShS-Intro

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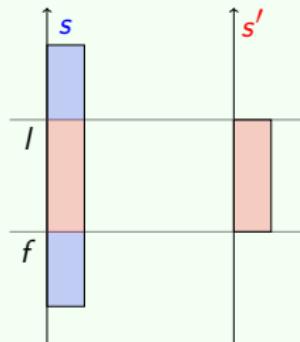
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## Illustration



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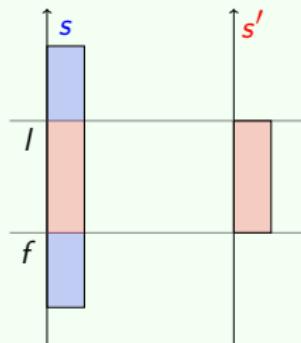
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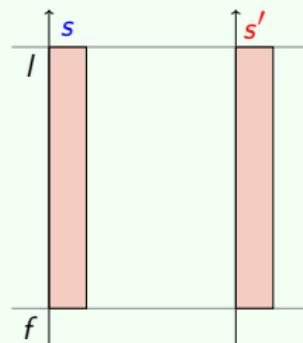
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## Illustration

if  $f_s = f \wedge l_s = l$  then:

- $s = s'$ .



## Reasoning over weak-equivalency and shared-slices

---

$$\text{Get-Over-WEq} \quad \frac{\text{get}(s_1, i) = v \quad s_1 \xleftrightarrow{K} s_2}{}$$

## Reasoning over weak-equivalency and shared-slices

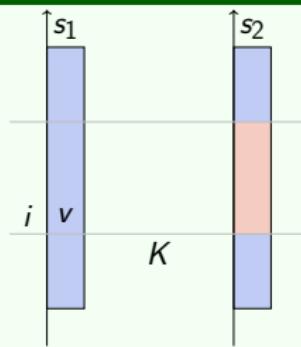
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$$\text{Get-Over-WEq} \frac{\text{get}(s_1, i) = v \quad s_1 \xleftrightarrow{K} s_2}{i < f_{s_1} \vee i > l_{s_1}} \quad ||$$

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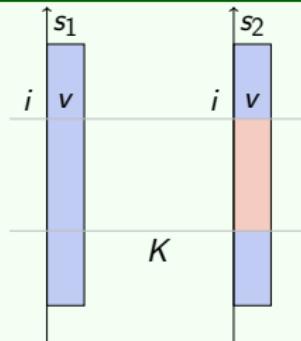
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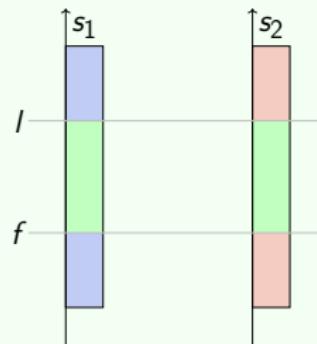
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# Reasoning over weak-equivalency and shared-slices

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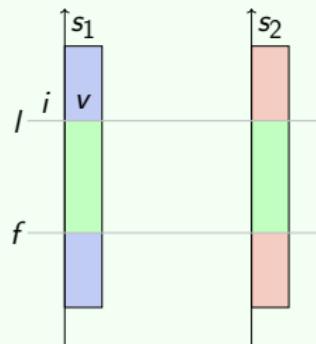
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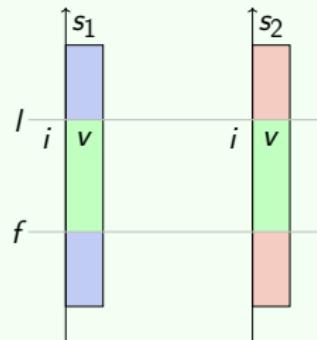
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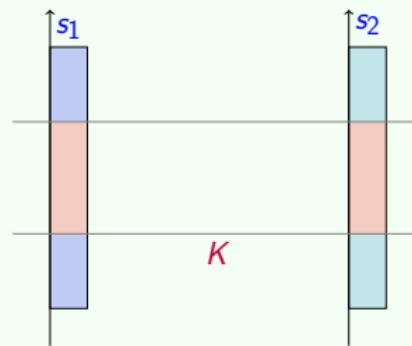
## Illustration



# Extensionality with NS-ShS

Ext-ShS  $s_1 \xleftrightarrow{K} s_2$

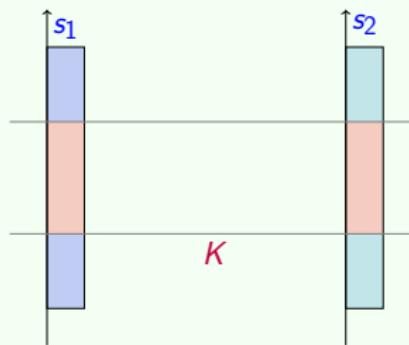
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# Extensionality with NS-ShS

$$\text{Ext-ShS} \quad \begin{array}{c} s_1 \xleftrightarrow{K} s_2 \\ s_1 = s_2 \end{array} \quad \parallel$$

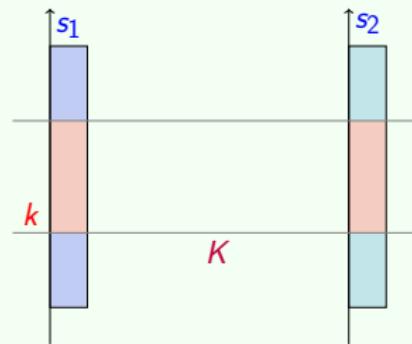
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# Extensionality with NS-ShS

$$\text{Ext-ShS} \quad \begin{array}{c} s_1 \xleftrightarrow{K} s_2 \\ s_1 = s_2 \\ \exists k \in K. \ f_{s_1} \leq k \leq l_{s_1} \wedge \end{array} \quad \parallel$$

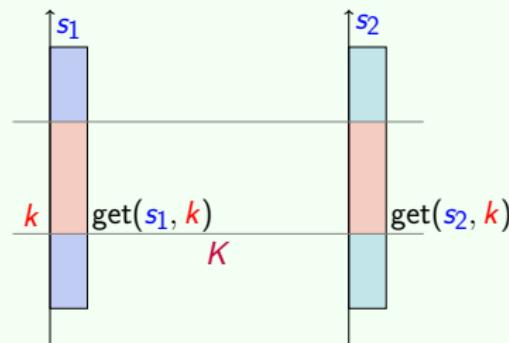
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# Extensionality with NS-ShS

$$\frac{\text{Ext-ShS} \quad s_1 \xleftrightarrow{K} s_2}{\exists k \in K. f_{s_1} \leq k \leq l_{s_1} \wedge \text{get}(s_1, k) \neq \text{get}(s_2, k) \wedge \dots} \quad ||$$

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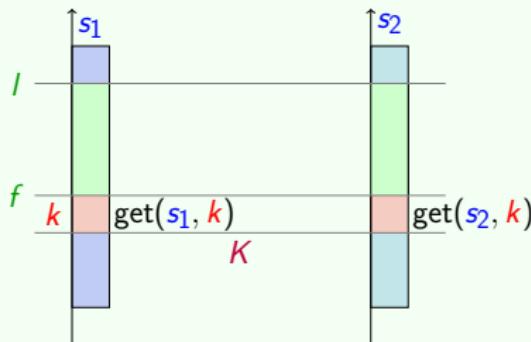


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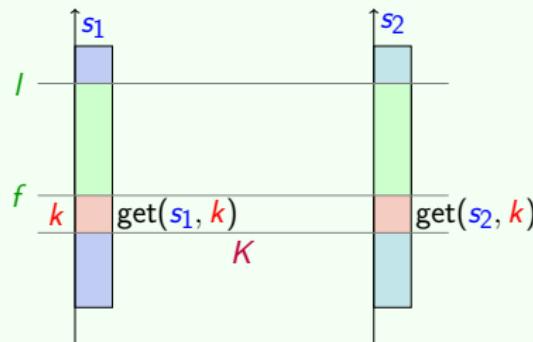


# Extensionality with NS-ShS

Ext-ShS

$$\frac{s_1 \xleftrightarrow{K} s_2}{\begin{array}{c} s_1 = s_2 \\ \exists k \in K. f_{s_1} \leq k \leq l_{s_1} \wedge \text{get}(s_1, k) \neq \text{get}(s_2, k) \wedge \\ \forall f, l. s_1 =_{[f;l]} s_2 \implies k < f \vee k > l \wedge \\ s_1 \neq s_2 \end{array} ||}$$

## Illustration



# Calculi Summary: NS-BASE, NS-EXT and NS-ShS

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Operations	NS-BASE	NS-EXT	NS-ShS
get set	String reasoning	Array reasoning	Array reasoning
concat slice update ...	String reasoning	String reasoning	Lazy (Shared-slices) reasoning

# Outline

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## 1. The SMT theory of n-Indexed Sequences

## 2. Reasoning over n-Indexed Sequences

- Using existing theories
- Porting calculi on Sequences to n-Sequences
- The Shared-Slices calculus
- Reasoning over relocation

## 3. Implementation

- Context
- Equivalence modulo relocation
- Constraint factorization
- Encoding sequences over n-Indexed Sequences

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# Reasoning over relocation 1

## Definition (Equivalence modulo relocation)

Given  $s_1$  and  $s_2$  two n-indexed sequences, equivalence modulo relocation is denoted with the relation  $s_1 =_{reloc} s_2$ , such that:

$$\begin{aligned} s_1 =_{reloc} s_2 \equiv \\ l_{s_2} = l_{s_1} - f_{s_1} + f_{s_2} \wedge \\ \forall i : \text{Int}, f_{s_1} \leq i \leq l_{s_1} \Rightarrow \text{get}(s_1, i) = \text{get}(s_2, i - f_{s_1} + f_{s_2}) \end{aligned}$$

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This reasoning is used for all the three calculi: NS-BASE, NS-EXT and NS-ShS.

## Reasoning over relocation 2

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- ▶ Applying NS-Comp-Reloc and Get-Reloc eagerly can be **costly**.

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- ▶ Applying NS-Comp-Reloc and Get-Reloc eagerly can be **costly**.
- ▶ Our extension to the union-find data structure helps mitigate that.

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## Implementation context

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NS-Base, NS-Ext and NS-ShS were implemented in Colibri2:

- ▶ A reimplementation in OCaml of the COLIBRI CP solver.
- ▶ A CP solver used to reason over SMT problems.
- ▶ That does not use a SAT solver or clause learning.
- ▶ Compensates with (abstract) domains, propagations and scheduling.

# Outline

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## Equivalence modulo relocation I

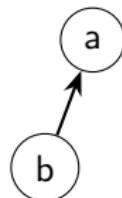
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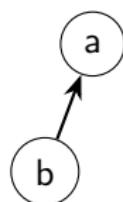
`union(a, b)`



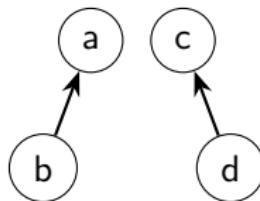
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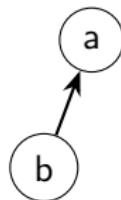
$\text{union}(c, d)$



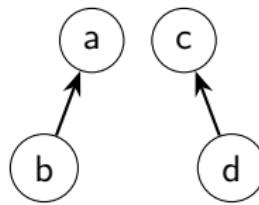
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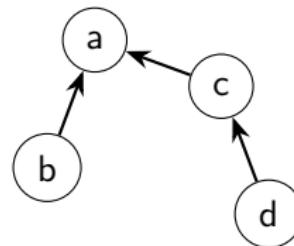
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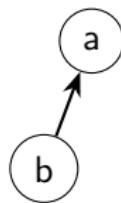
union(c,a)



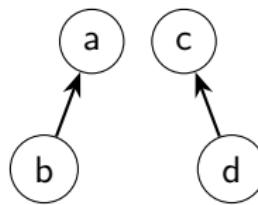
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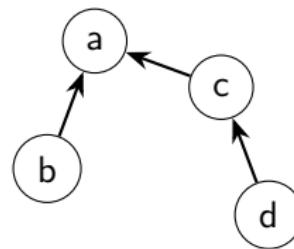
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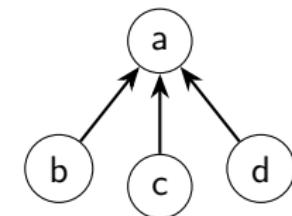
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$\text{find}(d) = a$



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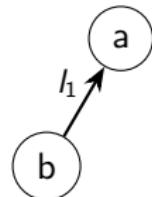
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Labeled union-find is an extension of union-find in which the relation between elements is parametrized (labeled).

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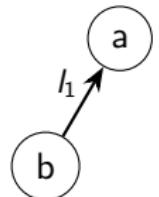
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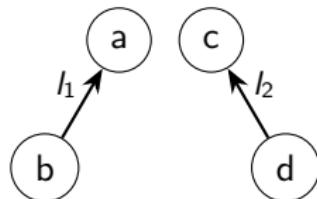
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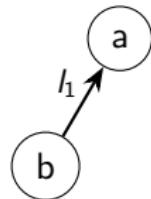
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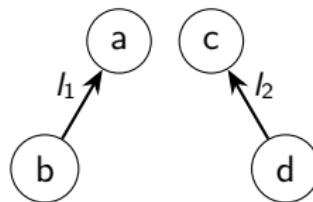
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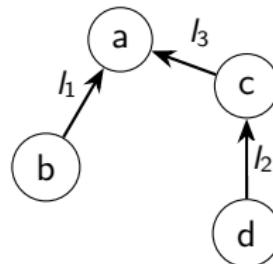
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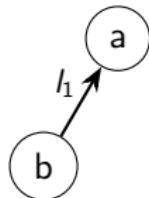
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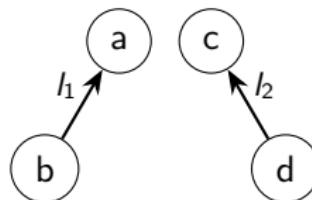
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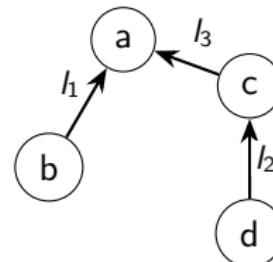
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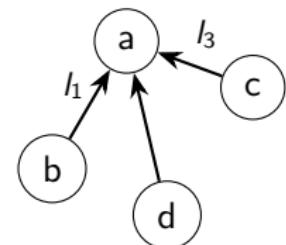
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`find(d) = a,`



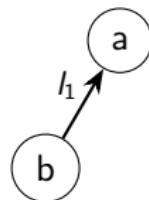
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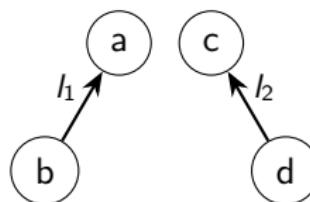
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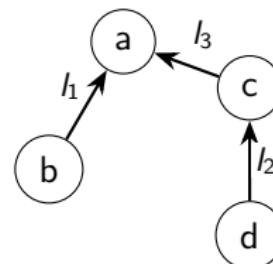
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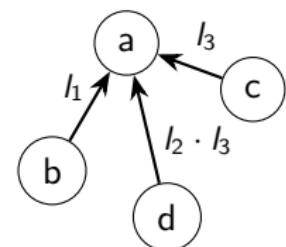
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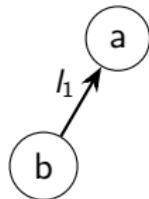
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The labels have a **composition operation** that:

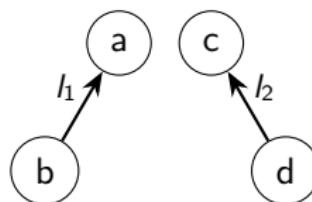
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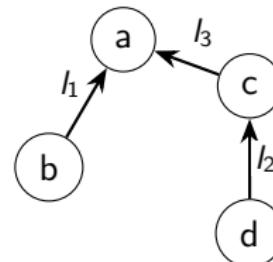
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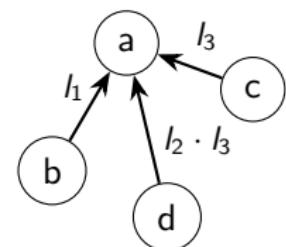
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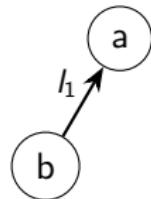
The labels have a **composition operation** that:

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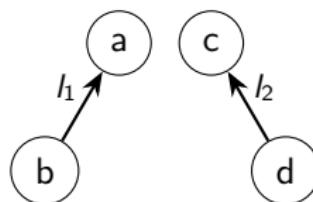
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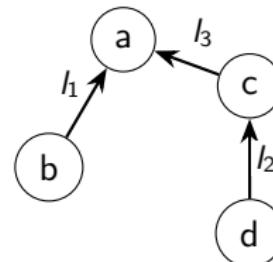
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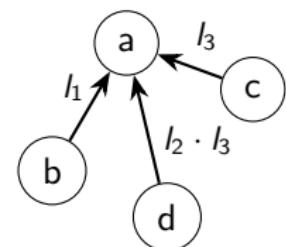
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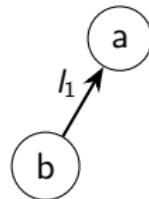
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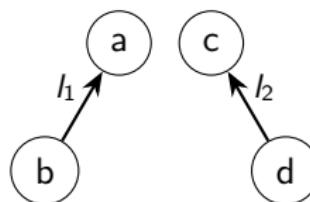
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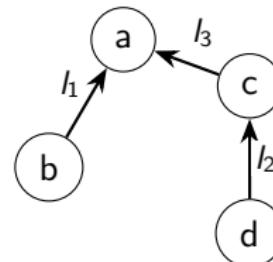
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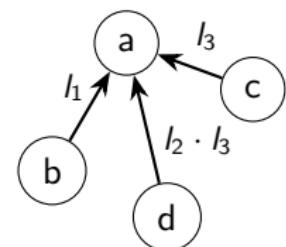
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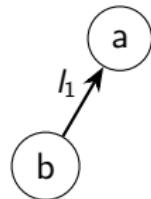
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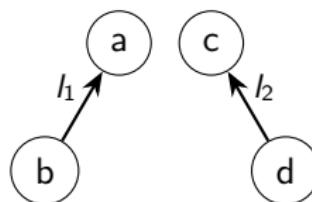
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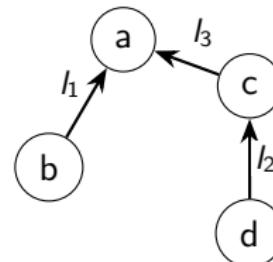
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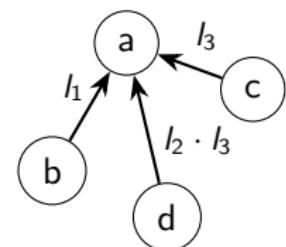
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- ▶ Is associative.
- ▶ Has an identity element.

Forming a **group** with the labels.

## Equivalence modulo relocation II

---

In the **labeled union-find** used to represent equivalence modulo relocation:

## Equivalence modulo relocation II

---

In the **labeled union-find** used to represent equivalence modulo relocation:

- ▶ Nodes: n-sequences.

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In the **labeled union-find** used to represent equivalence modulo relocation:

- ▶ Nodes: n-sequences.
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## Equivalence modulo relocation II

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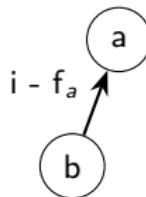
- ▶ Nodes: n-sequences.
- ▶ Labels: linear polynomials.
- ▶ Composition operation: integer addition.

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In the **labeled union-find** used to represent equivalence modulo relocation:

- ▶ Nodes: n-sequences.
- ▶ Labels: linear polynomials.
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$b = \text{relocate}(a, i)$

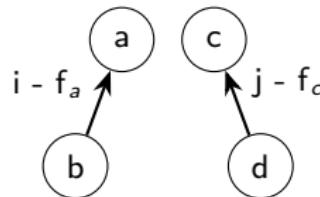
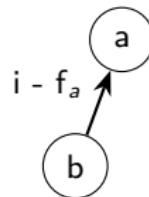


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- ▶ Nodes: n-sequences.
- ▶ Labels: linear polynomials.
- ▶ Composition operation: integer addition.

$$b = \text{relocate}(a, i) \quad d = \text{relocate}(c, j)$$

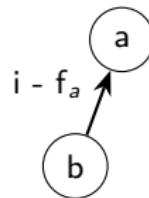


## Equivalence modulo relocation II

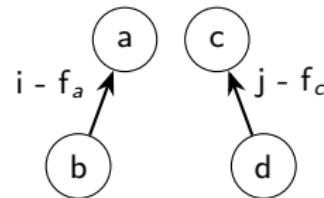
In the **labeled union-find** used to represent equivalence modulo relocation:

- ▶ Nodes: n-sequences.
- ▶ Labels: linear polynomials.
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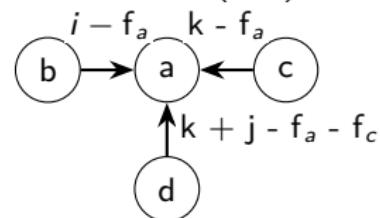
$$b = \text{relocate}(a, i)$$



$$d = \text{relocate}(c, j)$$



$$c = \text{relocate}(a, k)$$

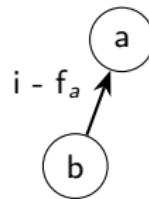


# Equivalence modulo relocation II

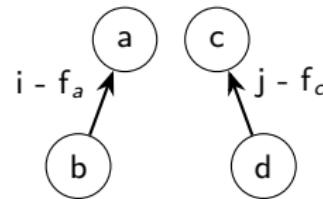
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- ▶ Nodes: n-sequences.
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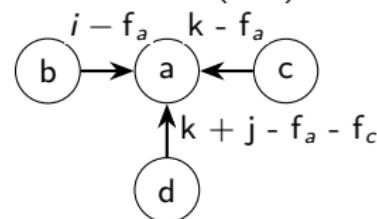
$$b = \text{relocate}(a, i)$$



$$d = \text{relocate}(c, j)$$



$$c = \text{relocate}(a, k)$$



In the implementation, it also holds a domain:

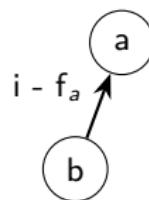
$$r \mapsto M : \left\{ \begin{array}{l} 0 \mapsto r \\ \delta_1 \mapsto s_1 \\ \dots \\ \delta_n \mapsto s_n \end{array} \right\}$$

# Equivalence modulo relocation II

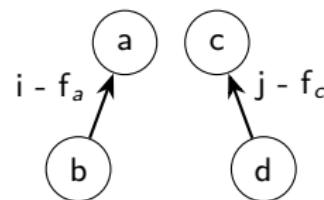
In the **labeled union-find** used to represent equivalence modulo relocation:

- ▶ Nodes: n-sequences.
- ▶ Labels: linear polynomials.
- ▶ Composition operation: integer addition.

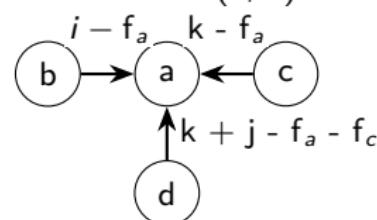
$$b = \text{relocate}(a, i)$$



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In the implementation, it also holds a domain:

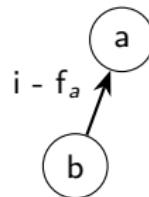
$$r \mapsto M : \left\{ \begin{array}{l} 0 \mapsto r \\ \delta_1 \mapsto s_1 \\ \dots \\ \delta_n \mapsto s_n \end{array} \right\} \cup \{\delta_i \mapsto s'_i\}$$

# Equivalence modulo relocation II

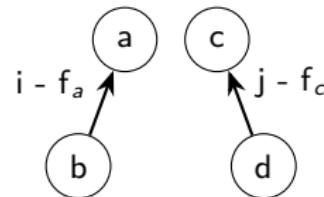
In the **labeled union-find** used to represent equivalence modulo relocation:

- ▶ Nodes: n-sequences.
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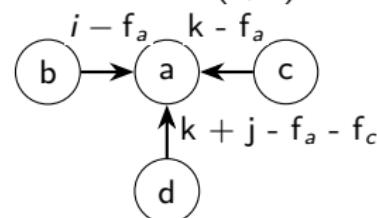
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$$c = \text{relocate}(a, k)$$



In the implementation, it also holds a domain:

$$r \mapsto M : \left\{ \begin{array}{l} 0 \mapsto r \\ \delta_1 \mapsto s_1 \\ \dots \\ \delta_n \mapsto s_n \end{array} \right\} \cup \{ \delta_i \mapsto s'_i \} \rightarrow \delta_i \in \text{Dom}(M) \implies s'_i = s_i$$

# Outline

---

## 1. The SMT theory of n-Indexed Sequences

## 2. Reasoning over n-Indexed Sequences

- Using existing theories
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- The Shared-Slices calculus
- Reasoning over relocation

## 3. Implementation

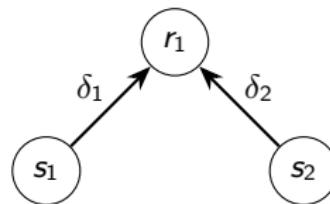
- Context
- Equivalence modulo relocation
- **Constraint factorization**
- Encoding sequences over n-Indexed Sequences

## 4. Experimental Evaluation

## 5. Conclusion

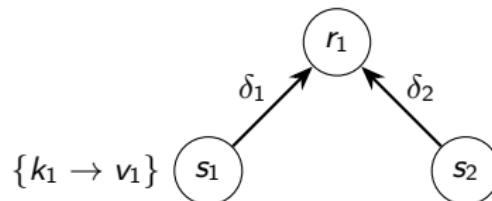
# Constraint factorization

---



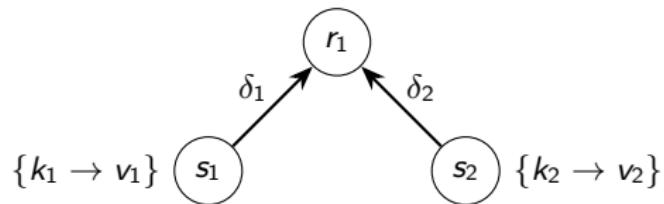
# Constraint factorization

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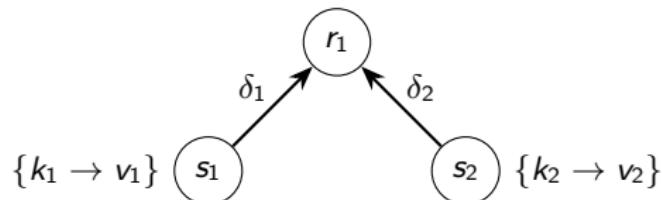


# Constraint factorization

---

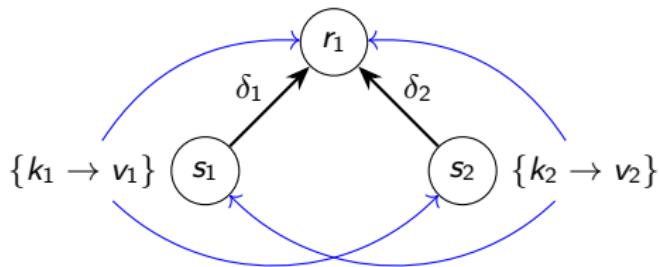


# Constraint factorization



$$\text{Get-Reloc} \frac{v = \text{get}(s, i) \quad s =_{\text{reloc}} r}{i < f_s \vee l_s < i \quad || \quad f_s \leq i \leq l_s \wedge v = \text{get}(r, i - f_s + f_r)}$$

# Constraint factorization



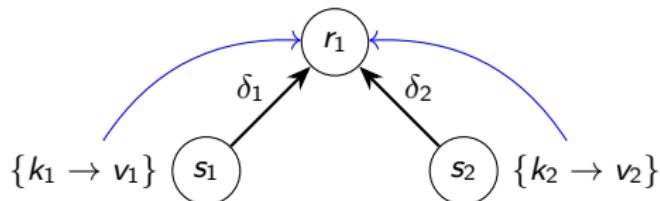
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# Constraint factorization

$$\begin{array}{c} \left\{ \begin{array}{l} k_2 - \delta_2 \rightarrow v_2 \\ k_1 - \delta_1 \rightarrow v_1 \end{array} \right\} \\ \\ \begin{array}{c} r_1 \\ \swarrow \delta_1 \qquad \searrow \delta_2 \\ s_1 \qquad \qquad \qquad s_2 \end{array} \\ \left\{ \begin{array}{l} k_1 \rightarrow v_1 \\ k_2 \rightarrow v_2 - \delta_2 + \delta_1 \end{array} \right\} \qquad \left\{ \begin{array}{l} k_2 \rightarrow v_2 \\ k_1 - \delta_1 + \delta_2 \rightarrow v_1 \end{array} \right\} \end{array}$$

$$\text{Get-Reloc} \quad \frac{v = \text{get}(s, i) \quad s =_{\text{reloc}} r}{i < f_s \vee l_s < i \quad || \quad f_s \leq i \leq l_s \wedge v = \text{get}(r, i - f_s + f_r)}$$

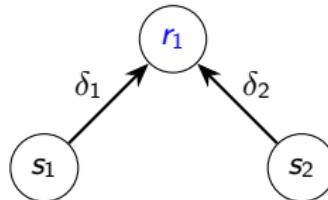
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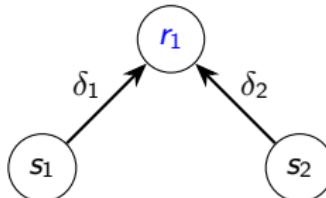


Get-Reloc

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$$\text{Get-Reloc} \quad \frac{v = \text{get}(s, i) \quad s =_{\text{reloc}} r}{i < f_s \vee l_s < i \quad \parallel \quad f_s \leq i \leq l_s \wedge v = \text{get}(r, i - f_s + f_r)}$$

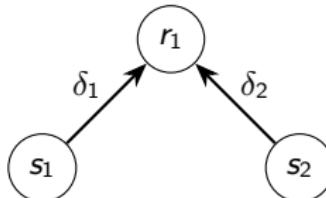
Also applies to NS-Comp-Reloc:

$$\text{NS-Comp-Reloc} \quad \frac{s = k_1 :: k_2 :: \dots :: k_n \quad s =_{\text{reloc}} r}{r = \text{relocate}(k_1, f_r) :: \text{relocate}(k_2, f_{k_2} - f_s + f_r) :: \dots :: \text{relocate}(k_n, f_{k_n} - f_s + f_r)}$$

# Constraint factorization

---

$$\begin{cases} k_2 - \delta_2 \rightarrow v_2 \\ k_1 - \delta_1 \rightarrow v_1 \end{cases}$$



To read more on how it is used in arithmetic reasoning:

► **"Relational Abstractions Based on Labeled Union-Find"**

Dorian Lesbre, Matthieu Lemere, Hichem Rami Ait-El-Hara, and François Bobot. [PLDI 2025](#)

# Outline

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1. The SMT theory of n-Indexed Sequences
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  - **Encoding sequences over n-Indexed Sequences**
4. Experimental Evaluation
5. Conclusion

## Encoding sequences over n-Indexed Sequences

---

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- ▶ Each sequences  $s$ : An  $n$ -sequence with  $f_s = 0$  and  $l_s \geq -1$

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---

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- ▶  $\text{seq.empty}$ : Represented by a special constant symbol  $\epsilon$ , an empty  $n$ -sequence with  $f_\epsilon = 0$  and  $l_\epsilon = -1$ .
- ▶  $\text{seq.}++(s_1, s_2, s_3, \dots, s_n)$ :

```
let(c1, concat(s1, relocate(s2, ls1 + 1))),  
let(c2, concat(c1, relocate(s3, lc1 + 1))),  
...  
concat(cn-2, relocate(sn, lcn-2 + 1))))
```

# Outline

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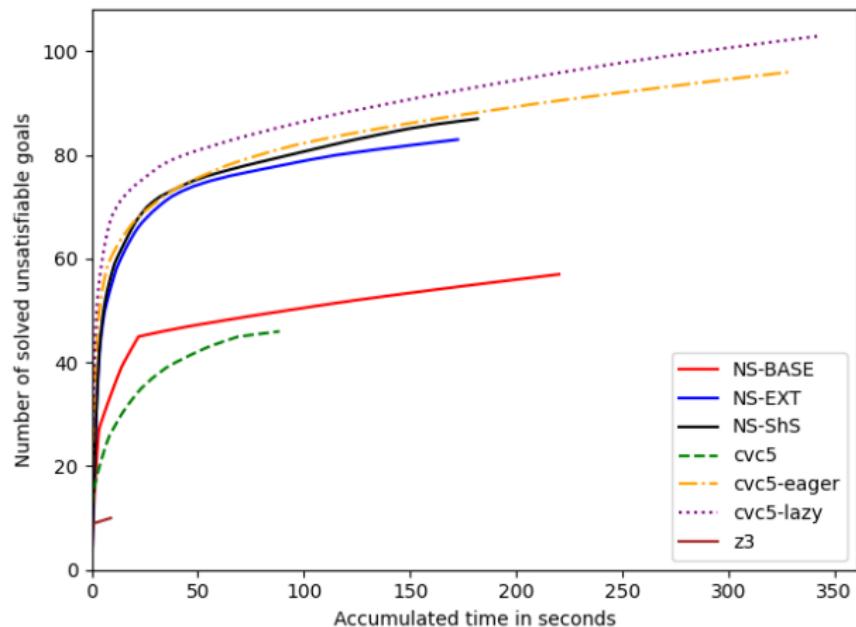
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## Experimental evaluation: context

---

- ▶ The experimentation was done on quantifier free sequence and n-sequence benchmarks, containing only sequence and n-sequence operations.
- ▶ The experimentation compares implementations of NS-BASE, NS-EXT and NS-ShS in Colibri2 with:
  - ▶ Sequence support in cvc5 and Z3.
  - ▶ Support for n-sequences encoded with ADTs and Sequences in cvc5 and Z3.

## Experimental evaluation: UNSAT Seq



**Figure:** Number of solved goals by accumulated time (in seconds) on unsatisfiable quantifier-free Sequence benchmarks.

## Experimental evaluation: SAT Seq

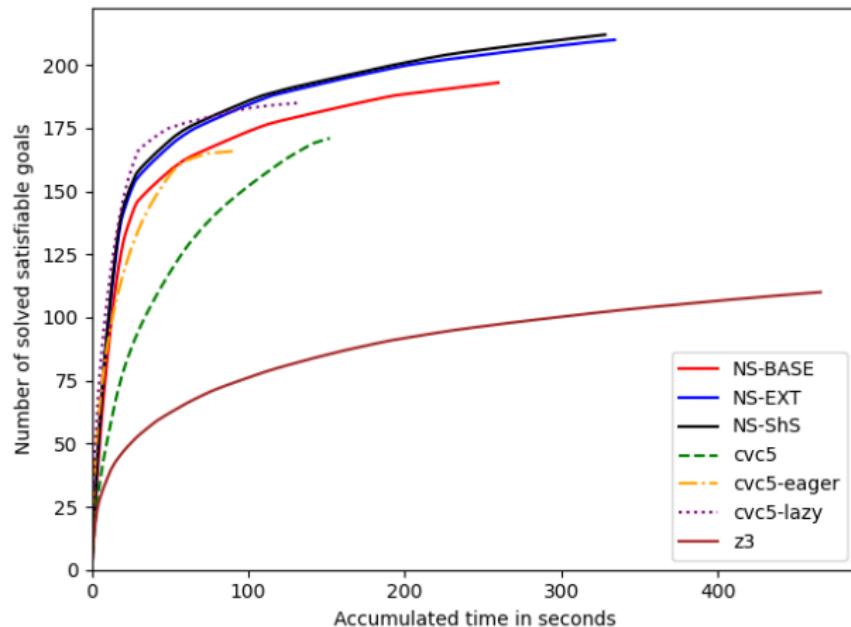


Figure: Number of solved goals by accumulated time (in seconds) on satisfiable quantifier-free Sequence benchmarks.

## Experimental evaluation: UNSAT NSeq

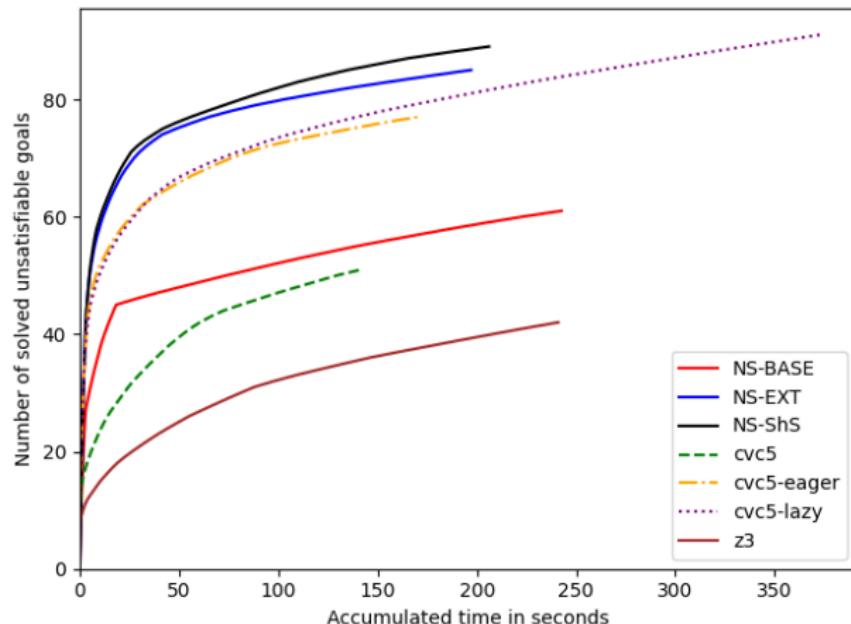
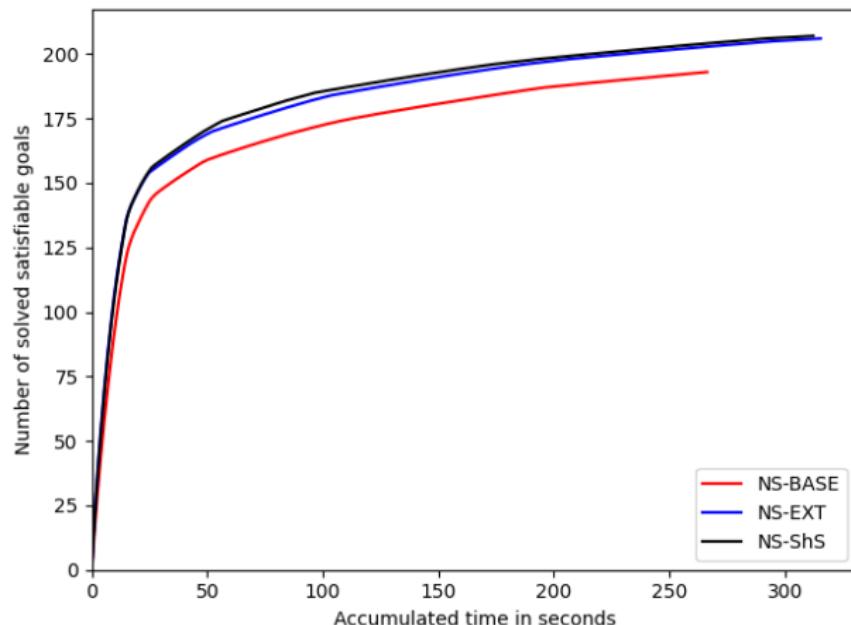


Figure: Number of solved goals by accumulated time (in seconds) on unsatisfiable quantifier-free  $n$ -Indexed Sequence benchmarks.

## Experimental evaluation: SAT NSeq



**Figure:** Number of solved goals by accumulated time (in seconds) on satisfiable quantifier-free  $n$ -Indexed Sequence benchmarks.

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---

# Conclusion

---

Contributions presented in this talk:

- ▶ The theory of n-Indexed Sequences.
- ▶ Various ways to reason over it.
- ▶ Experimental evaluation.

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- ▶ Various ways to reason over it.
- ▶ Experimental evaluation.

Additional contributions in the manuscript:

- ▶ Soundness proofs.
- ▶ Implementation details and formalizations.
- ▶ Work on real and integer arithmetic reasoning.  
(Labeled union-find for intervals and difference logic)

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Future work:

- ▶ Acquire more benchmarks
- ▶ Add  $(n)$ -sequences to Alt-Ergo
- ▶ Improve reasoning over  $n$ -sequences with quantifiers.

# Conclusion

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Contributions to software:

- ▶ Colibri2
- ▶ Alt-Ergo
- ▶ Smtml
- ▶ Dolmen
- ▶ SMT LSP

# Conclusion

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Contributions presented in this talk:

- ▶ The theory of  $n$ -Indexed Sequences.
- ▶ Various ways to reason over it.
- ▶ Experimental evaluation.

Additional contributions in the manuscript:

- ▶ Soundness proofs.
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(Labeled union-find for intervals and difference logic)

Future work:

- ▶ Acquire more benchmarks
- ▶ Add  $(n)$ -sequences to Alt-Ergo
- ▶ Improve reasoning over  $n$ -sequences with quantifiers.

Other:

- ▶ Co-supervised an intern for 6 months (Félix Loyau-Kahn, Master's student) on using AI for SMT solver selection.

Contributions to software:

- ▶ Colibri2
- ▶ Alt-Ergo
- ▶ Smtml
- ▶ Dolmen
- ▶ SMT LSP

# Publications

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- ▶ **"On SMT Theory Design: The Case of Sequences"**  
Hichem Rami Ait-El-Hara, François Bobot and Guillaume Bury. [LPAR 2024](#)
- ▶ **"An SMT Theory for n-Indexed Sequences"**  
Hichem Rami Ait-El-Hara, François Bobot, and Guillaume Bury. [SMT 2024](#)
- ▶ **"Reasoning over n-indexed sequences in SMT"**  
Hichem Rami Ait-El-Hara, François Bobot, and Guillaume Bury. [Acta Informatica 62.3 \(Aug. 2025\)](#)
- ▶ **"Relational Abstractions Based on Labeled Union-Find"**  
Dorian Lesbre, Matthieu Lemerre, Hichem Rami Ait-El-Hara, and François Bobot. [PLDI 2025](#)
- ▶ **"Constraint Propagation for Bit-Vectors in Alt-Ergo"**  
Hichem Rami Ait-El-Hara, Guillaume Bury, Basile Clément, and Pierre Villemot. [SMT 2025](#)

Preprints:

- ▶ **"Smt.ml: A Multi-Backend Frontend for SMT Solvers in OCaml"**  
João Madeira Pereira, Filipe Marques, Pedro Adão, Hichem Rami Ait-El-Hara, Léo Andrès, Arthur Carcano, Pierre Chambart, Nuno Santos, and José Fragoso Santos. [To be submitted to TACAS 2026](#).

# Appendix 1: bibliography I

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[Bjø+12] N Bjørner et al. "An SMT-LIB Format for Sequences and Regular Expressions". In: *Strings* (Jan. 2012).

[CH15] Jürgen Christ and Jochen Hoenicke. "Weakly Equivalent Arrays". In: *Frontiers of Combining Systems*. Ed. by Carsten Lutz and Silvio Ranise. Cham: Springer International Publishing, 2015, pp. 119–134. ISBN: 978-3-319-24246-0. DOI: 10.1007/978-3-319-24246-0\_8.

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[McC62] John McCarthy. "Towards a Mathematical Science of Computation". In: *Information Processing, Proceedings of the 2nd IFIP Congress 1962, Munich, Germany, August 27 - September 1, 1962*. North-Holland, 1962, pp. 21–28.

[She+23] Ying Sheng et al. "Reasoning About Vectors: Satisfiability Modulo a Theory of Sequences". In: *Journal of Automated Reasoning* 67.3 (Sept. 2023), p. 32. ISSN: 1573-0670. DOI: 10.1007/s10817-023-09682-2.

# Appendix

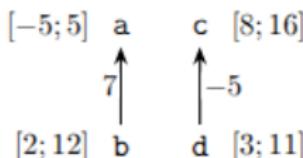
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6. Labeled Union-Find for Arithmetic reasoning

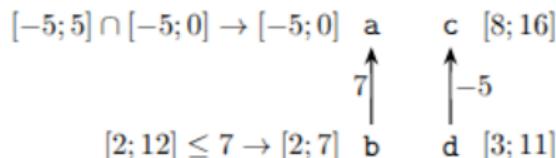
7. NS-BASE and NS-EXT

# Reduced Product

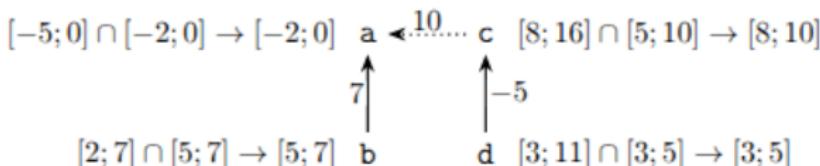
0. init:



1. assert  $(b \leq 7)$ :



2. repr\_change\_hook(c, 10, b):



3. end:

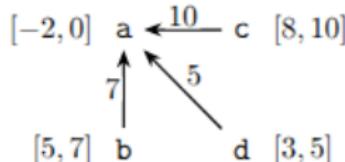
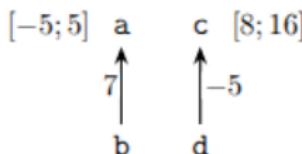


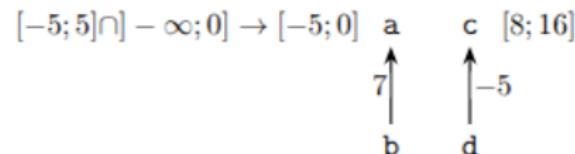
Figure 6.4: Example of the usage of the constant difference relation for constraint propagation over the domain of intervals.

# Group Action

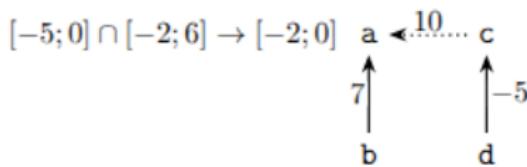
0. init:



1. assert ( $b \leq 7$ ):



2. repr\_change\_hook<sub>A<sub>I</sub></sub>(c, 10, b):



3. end:

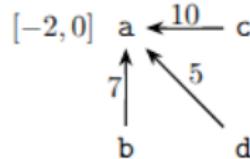


Figure 6.5: Example of the usage of the constant difference relation for constraint factorization over the domain of intervals.

# Normal forms

## Definition (NSeq term normal form)

For simplicity, we introduce the concatenation operator  $::$  with the invariant:

$$s \mapsto s_1 :: s_2 \implies f_s = f_{s_1} \wedge l_s = l_{s_2} \wedge f_{s_2} = l_{s_1} + 1$$

## Normalization

The following rewriting rules are applied whenever possible:

$$\begin{cases} s \mapsto [w_1 ::]x[:: w_2] \\ x \mapsto y :: z \end{cases} \rightarrow \begin{cases} s \mapsto [w_1 ::]y :: z[:: w_2] \\ x \mapsto y :: z \end{cases}$$

And if  $l_y < f_y$  is deduced:

$$\begin{cases} s \mapsto [w_1 ::]y :: z[:: w_2] \\ x \mapsto y :: z \end{cases} \rightarrow \begin{cases} s \mapsto [w_1 ::]z[:: w_2] \\ x \mapsto z \end{cases}$$