

# PhD. Defense

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## Theory of Sequences Tailored for Program Verification

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Théorie des séquences adaptée à la vérification des programmes

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by **Hichem Rami AIT EL HARA**<sup>1,2</sup>

Under the supervision of **François BOBOT**<sup>2</sup> and **Guillaume BURY**<sup>1</sup>

<sup>1</sup>OCamlPro

<sup>2</sup>Université Paris-Saclay, CEA, LIST



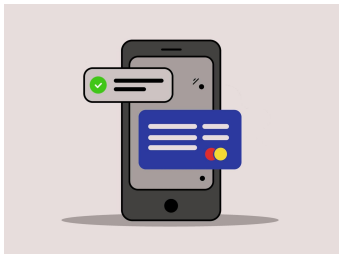
OCaml PRO



list

# Software is everywhere

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Personal information



Energy



Aerospace



Healthcare

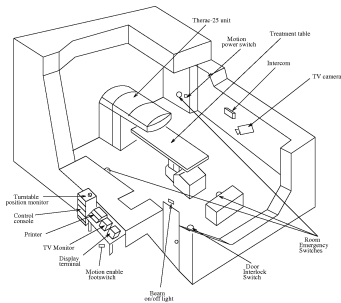
# And it can be faulty (bugged)



Ariane 5 \*

(Arithmetic overflow)

**Loss of over US\$370 million**



Therac-25 \*\*

(Race condition)

**Deaths and injuries of patients**

More examples:

[https://en.wikipedia.org/wiki/List\\_of\\_software\\_bugs](https://en.wikipedia.org/wiki/List_of_software_bugs)

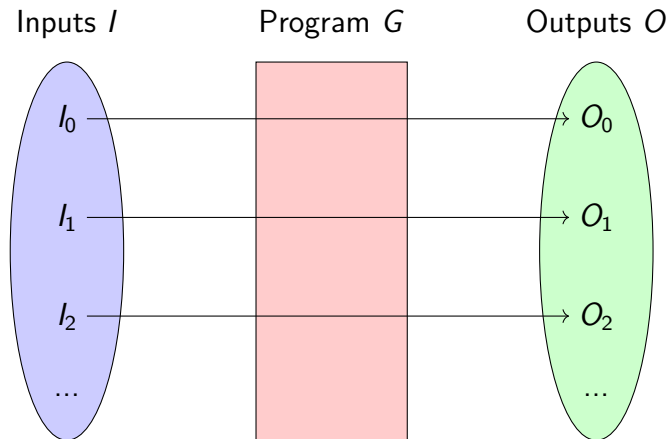
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\*Photo: ©ESA

\*\*Figure from: "Medical Devices: The Therac-25" by Nancy G. Leveson

## Behind the software, there are programs.

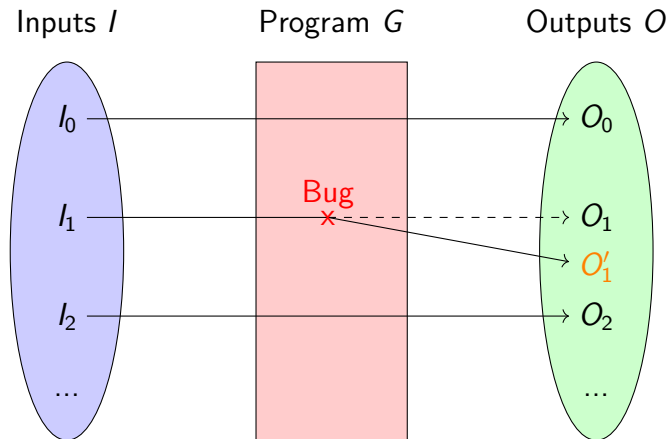
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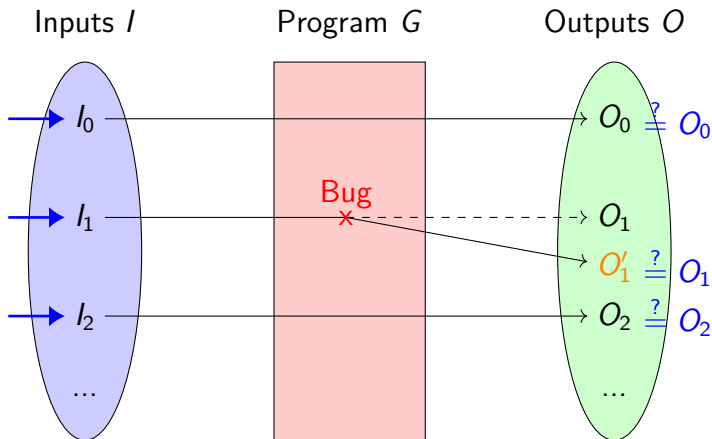
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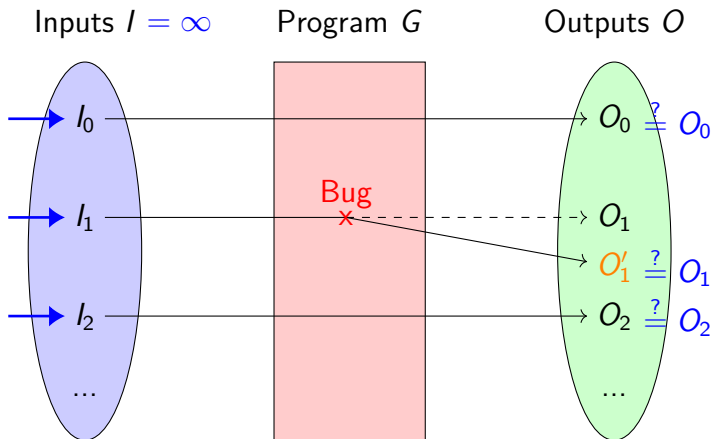
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## Testing



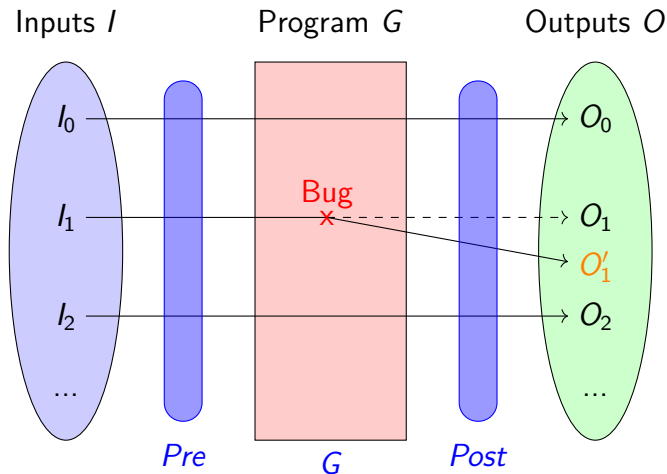
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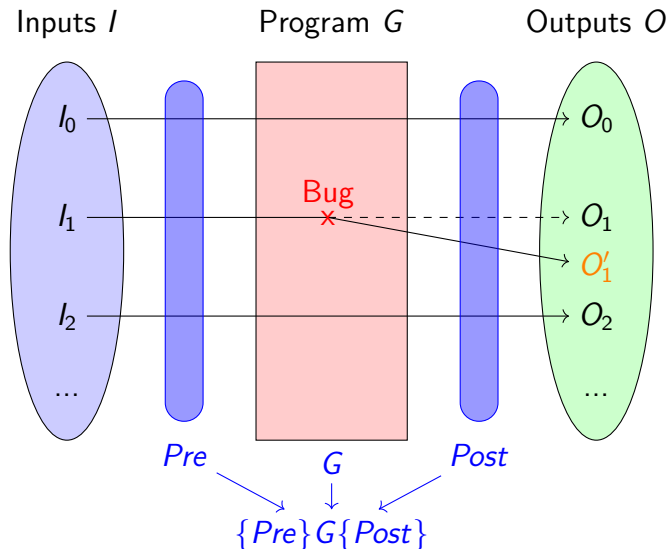
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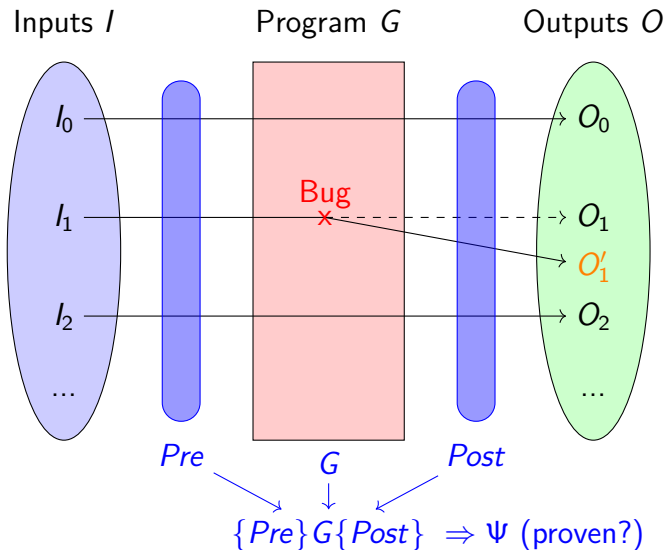
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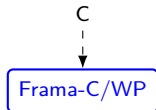


# Avoiding Bugs in the Real World

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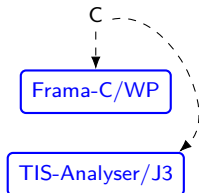
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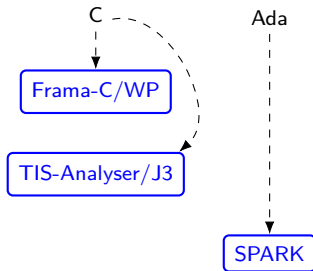
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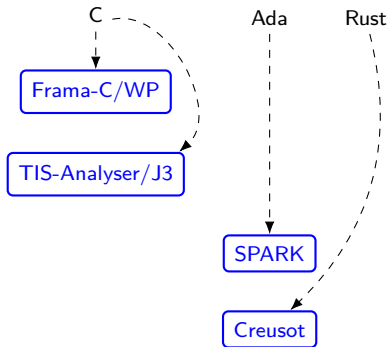
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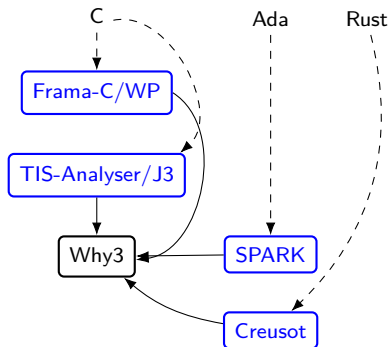
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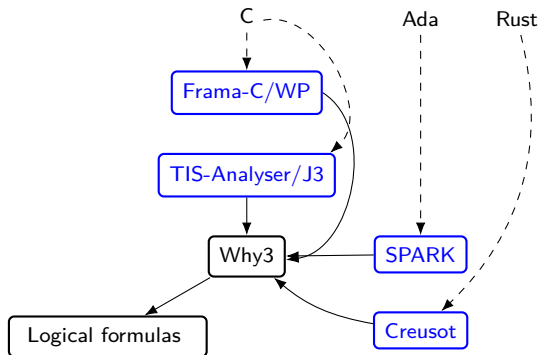
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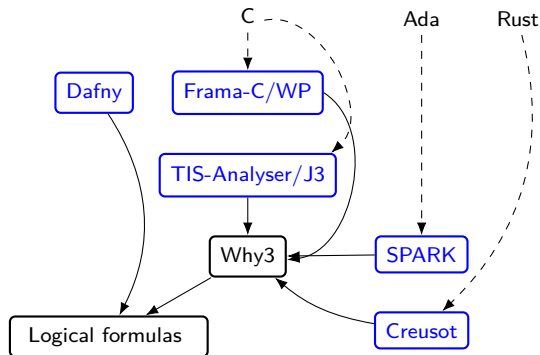


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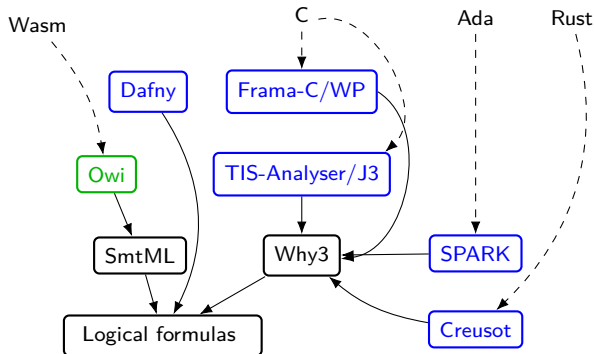
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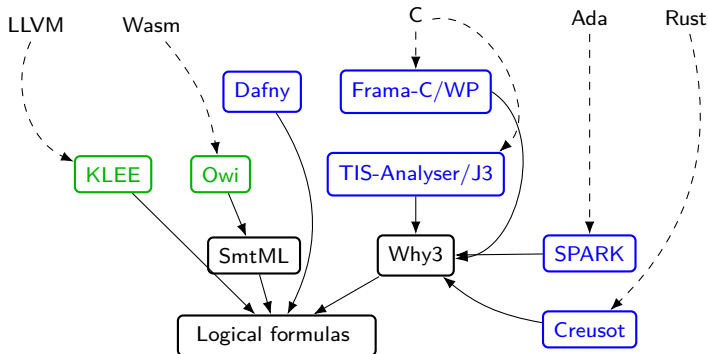
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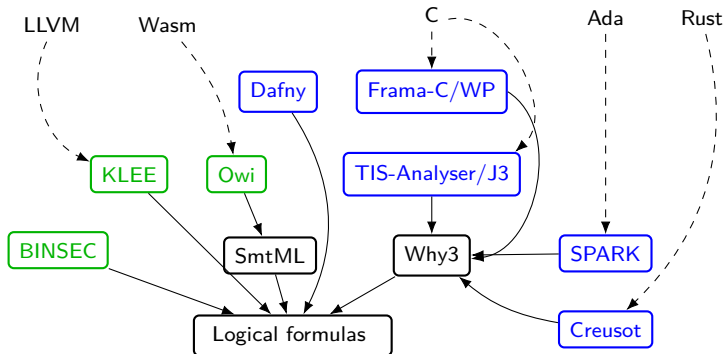


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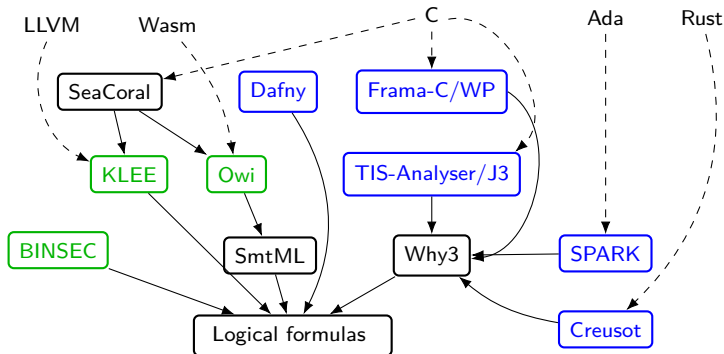




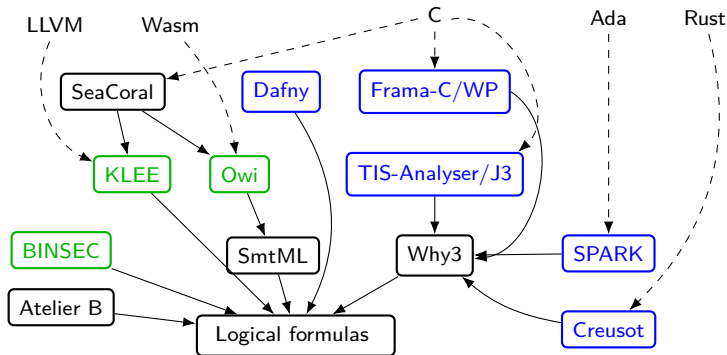
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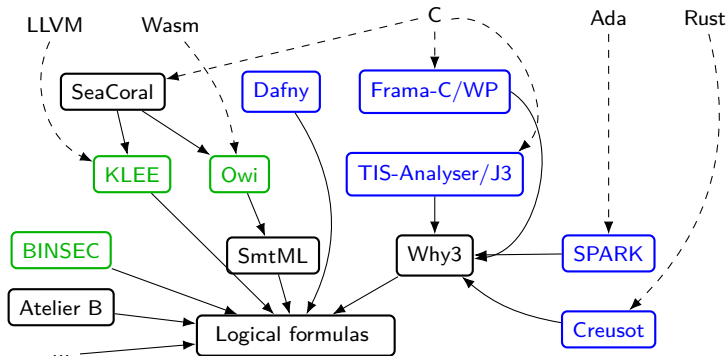
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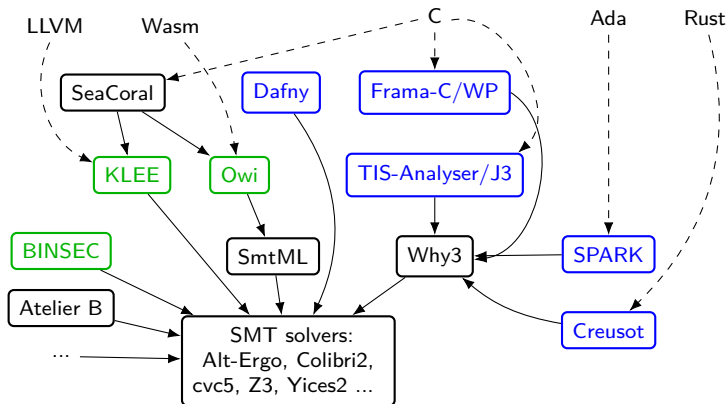
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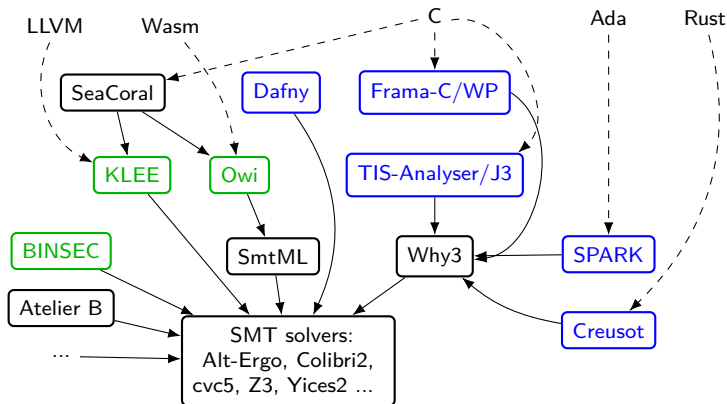
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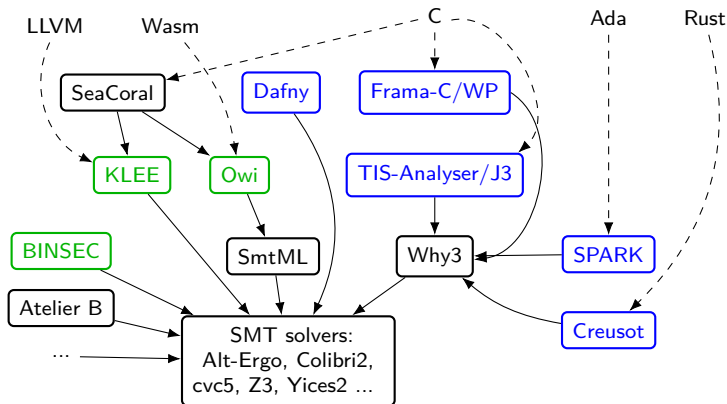


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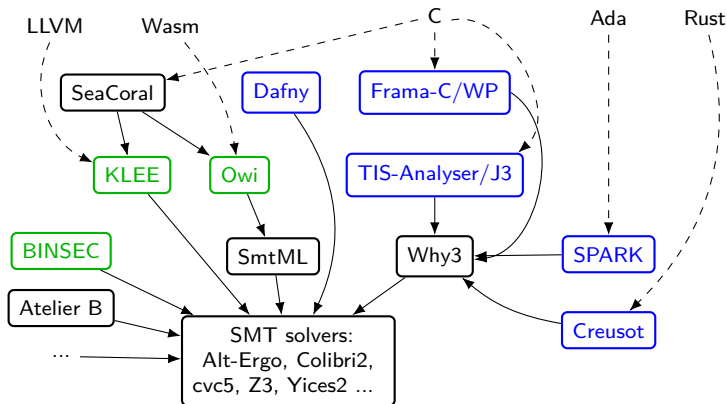
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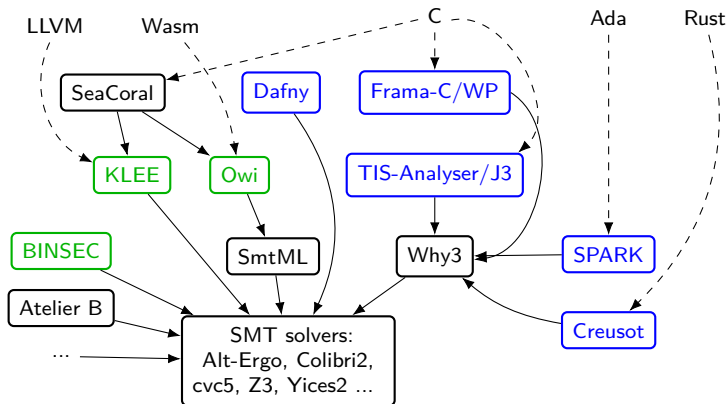


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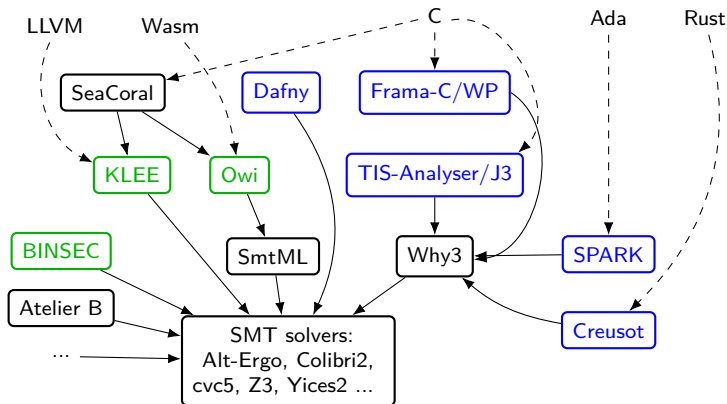
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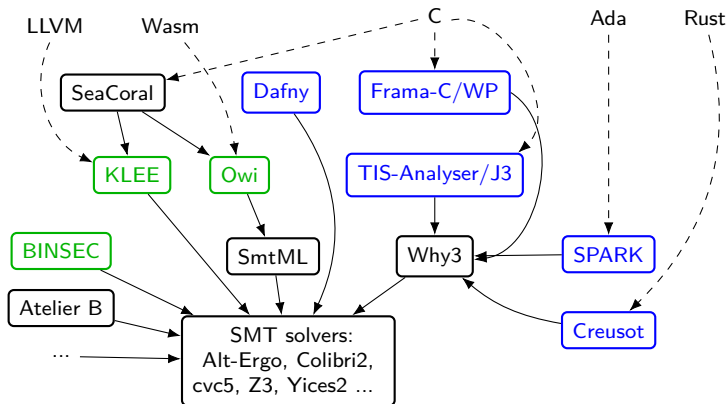
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Yes, therefore  $F$  is **satisfiable**.

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No, therefore  $F$  is **unsatisfiable**. Inversely  $\neg F$  is **valid**.

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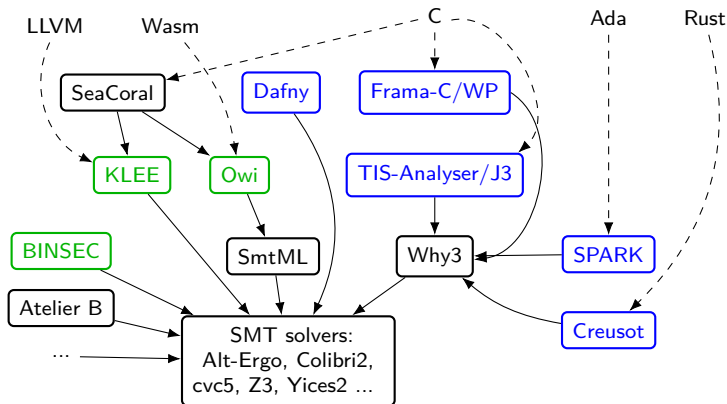
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# Avoiding Bugs in the Real World



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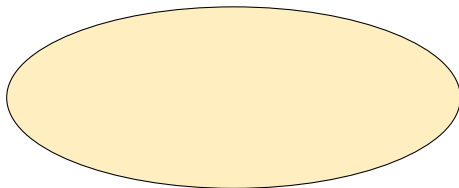
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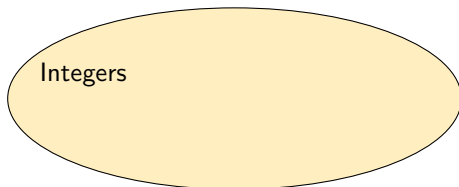


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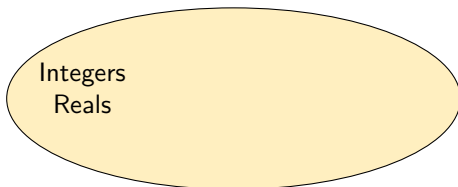


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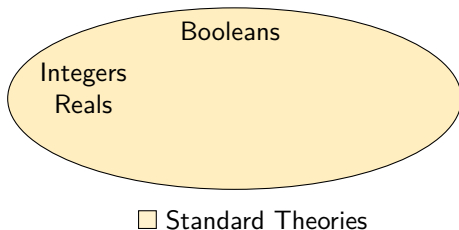


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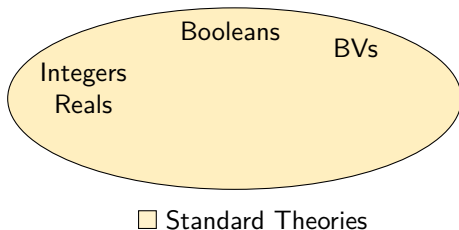
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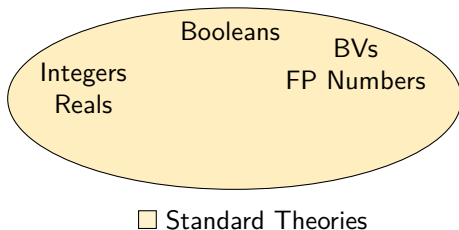
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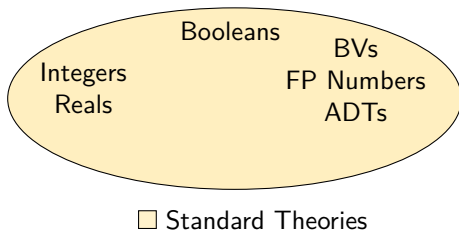
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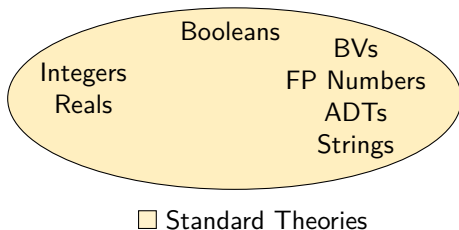




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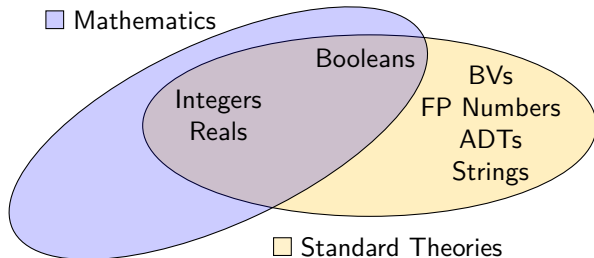
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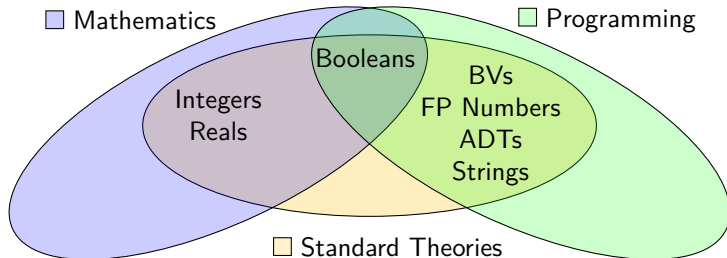
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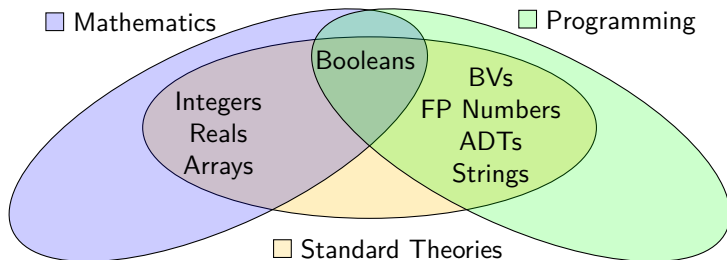
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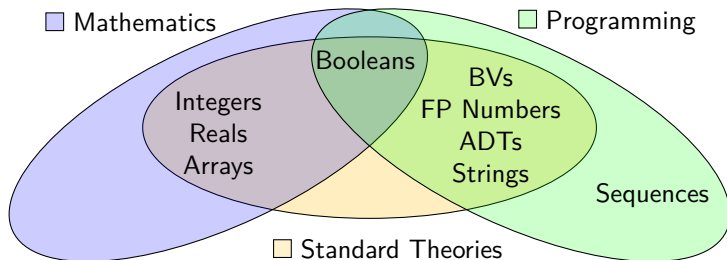
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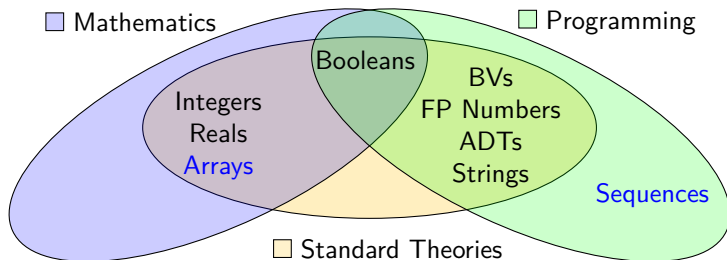
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# Why are SMT solvers used?

- ▶ Expressiveness (Quantifies and various theories)
- ▶ Efficiency (Combination of powerful decision procedures)
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# Arrays and Sequences in SMT

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Sequences are more suitable as they are semantically closer.

# In this thesis: A different theory of Sequences

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An n-indexed sequence (or n-sequence)  $s$  is a sequence that is indexed from a first index  $f_s$  to a last index  $l_s$ .

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- ▶ A generalization of the theory of sequences.

# Outline

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1. The SMT theory of  $n$ -Indexed Sequences
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## Empty n-indexed sequence

An  $n$ -indexed sequence  $s$  is said to be empty if  $l_s < f_s$ . Two empty  $n$ -indexed sequences  $a$  and  $b$  are equal only if  $f_a = f_b$  and  $l_a = l_b$ .

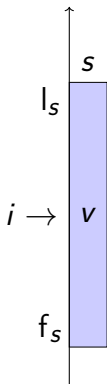
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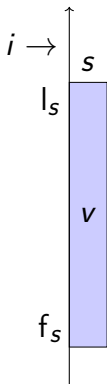
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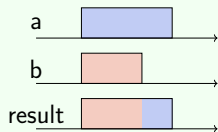
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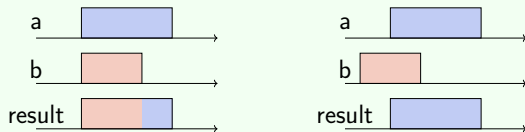
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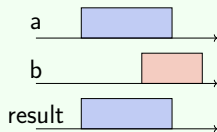
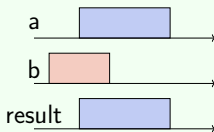
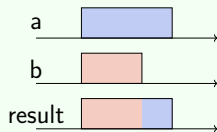




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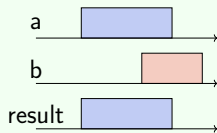
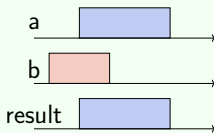
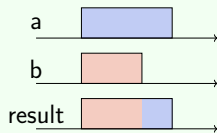
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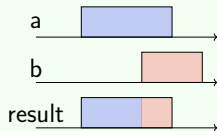
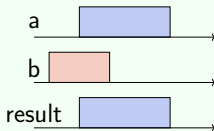
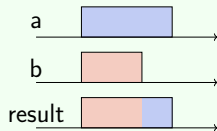
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In the theory of sequences (in cvc5)  $\text{update}(a, i, b)$ :



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To read more on SMT theory design and semantic choices:

- ▶ **"On SMT Theory Design: The Case of Sequences"**  
Hichem Rami Ait-El-Hara, François Bobot and Guillaume Bury. [LPAR 2024](#)

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## Extensionality

The theory of n-indexed sequences is extensional. Therefore, given two n-indexed sequences  $a$  and  $b$ :

$$\begin{aligned}(a = b) \equiv & \\ & (f_a = f_b \wedge l_a = l_b \wedge \\ & \forall i : \text{Int}, f_a \leq i \leq l_a \rightarrow \text{get}(a, i) = \text{get}(b, i))\end{aligned}$$

# Outline

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# Axiomatization/Encoding of n-Sequences

---

Axiomatization (with arrays):

- ▶ Most operations need to be axiomatized.
- ▶ Introduces too many quantified formulas.

Encoding using Sequences and Algebraic Data Types:

- ▶ Avoids using as many quantifiers.
- ▶ Depends on two other theories (Sequences and ADTs).
- ▶ Differences in the semantics make the definitions complex.



# Reasoning with Sequences and Algebraic Data Types I

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Except  $\text{const}(f, l, v)$ , which has **no counterpart** in the theory of sequences:

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Other symbols of the theory are defined over it:

- ▶  $f_n = n.fst$  and  $l_n = n.fst + \text{len}(n.seq) - 1$
- ▶  $\text{get}(n, i) = \text{nth}(n.seq, i - n.fst)$

Except  $\text{const}(f, l, v)$ , which has **no counterpart** in the theory of sequences:

- ▶ It can be axiomatized:

$$\begin{aligned} n = \text{const}(f, l, v) &\iff f_n = f \wedge l_n = l \wedge \\ &\forall i. f \leq i \leq l \implies \text{get}(n, i) = v \end{aligned}$$

# Outline

---

1. The SMT theory of n-Indexed Sequences
2. Reasoning over n-Indexed Sequences
  - Using existing theories
  - Porting calculi on Sequences to n-Sequences
  - The Shared-Slices calculus
  - Reasoning over relocation
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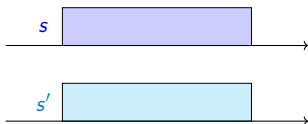
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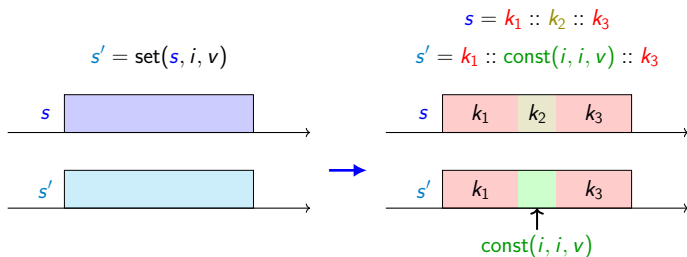
$$s' = \text{set}(s, i, v)$$



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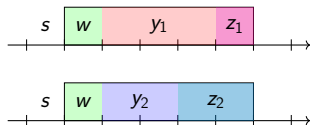
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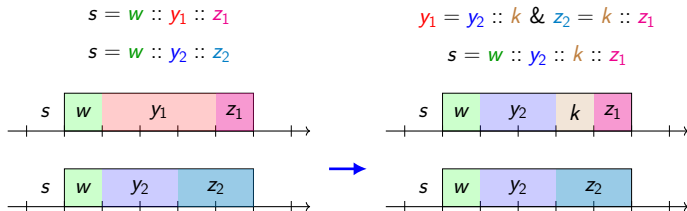
$$s = w :: y_2 :: z_2$$



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To read more on NS-BASE and NS-EXT:

- ▶ **"An SMT Theory for n-Indexed Sequences"**  
Hichem Rami Ait-El-Hara, François Bobot, and Guillaume Bury. [SMT 2024](#)
- ▶ **"Reasoning over n-indexed sequences in SMT"**  
Hichem Rami Ait-El-Hara, François Bobot, and Guillaume Bury. [Acta Informatica 62.3 \(Aug. 2025\)](#)

## Calculi Summary: NS-BASE and NS-EXT

---

Operations	NS-BASE	NS-EXT
get set	String reasoning	Array reasoning
concat slice update ...	String reasoning	String reasoning

Limitations:

- Eager normalization is often costly and sometimes unnecessary.

Alternative:

- A new calculus that lazily reasons over slices.



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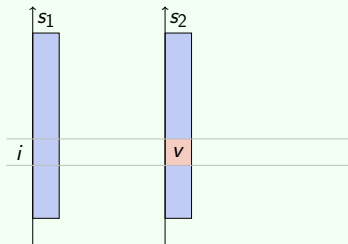
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## Illustration



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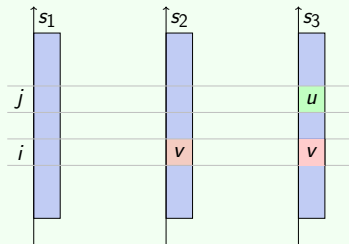
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## Illustration

Given  $s_3 = \text{set}(s_2, j, u)$ ,  
With  $f_{s_2} \leq j \leq l_{s_2}$ :

- $f_{s_2} = f_{s_3} \wedge l_{s_2} = l_{s_3}$
- $s_1 \stackrel{\{i, j\}}{\leftrightarrow} s_3$





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Slice-ShS-Intro

---

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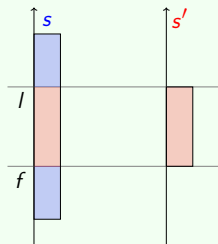
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## Illustration



# The Shared-Slices (NS-ShS) Calculus II

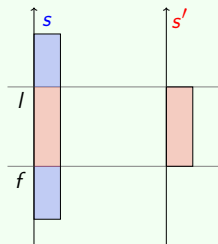
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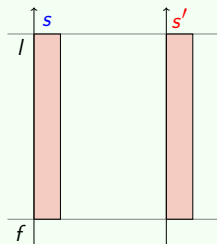
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## Illustration

if  $f_s = f \wedge l_s = l$  then:

►  $s = s'$ .



## Reasoning over weak-equivalency and shared-slices

---

$$\text{Get-Over-WEq} \frac{\text{get}(s_1, i) = v \quad s_1 \overset{K}{\leftrightarrow} s_2}{\quad}$$



## Reasoning over weak-equivalency and shared-slices

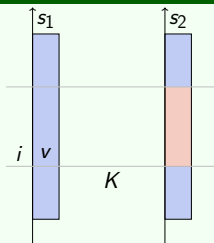
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$$\text{Get-Over-WEq} \frac{\text{get}(s_1, i) = v \quad s_1 \overset{K}{\leftrightarrow} s_2}{i < f_{s_1} \vee i > l_{s_1}} \quad ||$$

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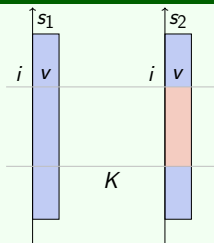
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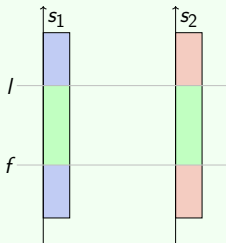
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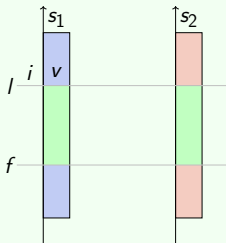
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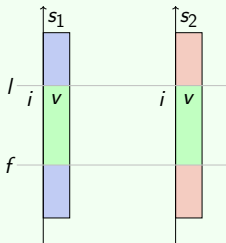
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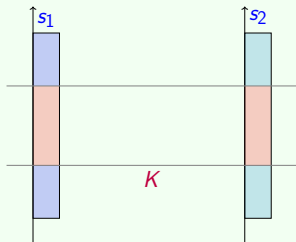
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# Extensionality with NS-ShS

Ext-ShS  $\xrightarrow{s_1 \overset{K}{\leftrightarrow} s_2}$

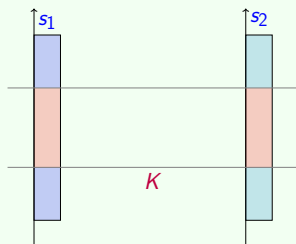
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# Extensionality with NS-ShS

$$\text{Ext-ShS} \text{ --- } \frac{s_1 \overset{K}{\leftrightarrow} s_2}{s_1 = s_2} \quad ||$$

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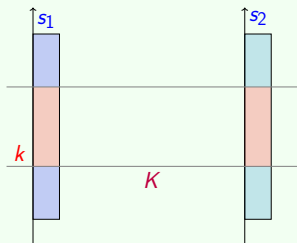




# Extensionality with NS-ShS

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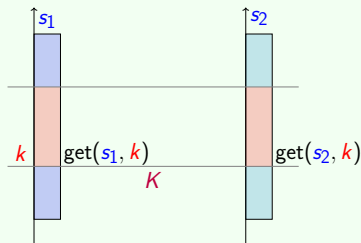
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$$\text{Ext-ShS} \frac{s_1 \overset{K}{\leftrightarrow} s_2}{\begin{array}{l} s_1 = s_2 \\ \exists k \in K. f_{s_1} \leq k \leq l_{s_1} \wedge \text{get}(s_1, k) \neq \text{get}(s_2, k) \wedge \end{array}} \parallel$$

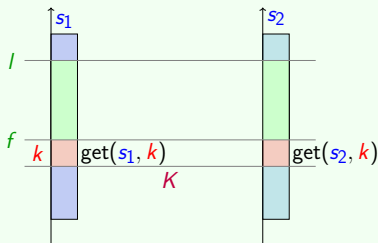
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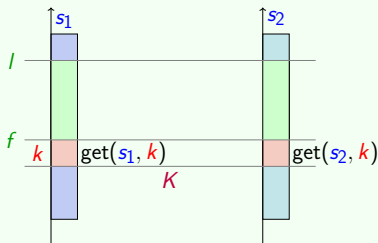
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## Calculi Summary: NS-BASE, NS-EXT and NS-ShS

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Operations	NS-BASE	NS-EXT	NS-ShS
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concat slice update ...	String reasoning	String reasoning	Lazy (Shared-slices) reasoning

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## Definition (Equivalence modulo relocation)

Given  $s_1$  and  $s_2$  two  $n$ -indexed sequences, equivalence modulo relocation is denoted with the relation  $s_1 =_{reloc} s_2$ , such that:

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This reasoning is used for all the three calculi: NS-BASE, NS-EXT and NS-ShS.

## Reasoning over relocation 2

---

$$\text{NS-Comp-Reloc} \frac{s = k_1 :: k_2 :: \dots :: k_n \quad s =_{\text{reloc}} r}{s =_{\text{reloc}} r}$$

## Reasoning over relocation 2

---

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- Applying NS-Comp-Reloc and Get-Reloc eagerly can be **costly**.

## Reasoning over relocation 2

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- ▶ Applying NS-Comp-Reloc and Get-Reloc eagerly can be **costly**.
- ▶ Our extension to the union-find data structure helps mitigate that.

# Outline

---

1. The SMT theory of n-Indexed Sequences
2. Reasoning over n-Indexed Sequences
  - Using existing theories
  - Porting calculi on Sequences to n-Sequences
  - The Shared-Slices calculus
  - Reasoning over relocation
3. Implementation
  - Context
  - Equivalence modulo relocation
  - Constraint factorization
  - Encoding sequences over n-Indexed Sequences
4. Experimental Evaluation
5. Conclusion

NS-Base, NS-Ext and NS-ShS were implemented in Colibri2:

- ▶ A reimplement in OCaml of the COLIBRI CP solver.
- ▶ A CP solver used to reason over SMT problems.
- ▶ That does not use a SAT solver or clause learning.
- ▶ Compensates with (abstract) domains, propagations and scheduling.

# Outline

---

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## Equivalence modulo relocation I

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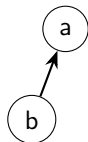
The equivalence modulo relocation relation is represented using a **labeled union-find**.

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union(a, b)

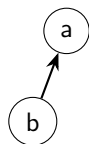




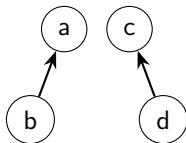
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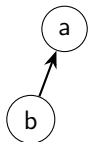
union(c, d)



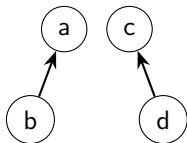
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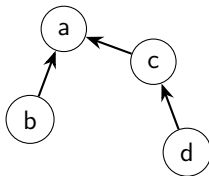
union(a, b)



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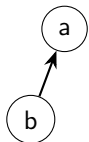
union(c,a)



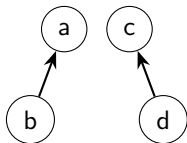
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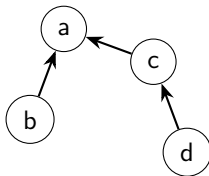
$\text{union}(a, b)$



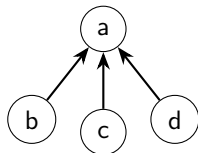
$\text{union}(c, d)$



$\text{union}(c, a)$



$\text{find}(d) = a$



# Equivalence modulo relocation I

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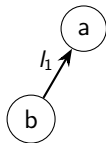
## Definition

Labeled union-find is an extension of union-find in which the relation between elements is parametrized (labeled).

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`add_relation(b,  $l_1$ , a)`



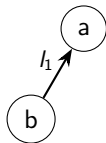
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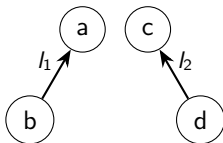
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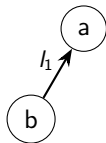
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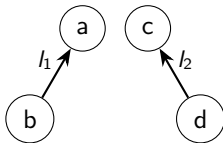
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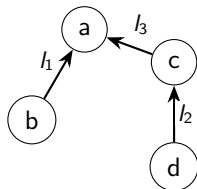
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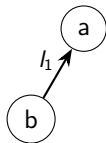
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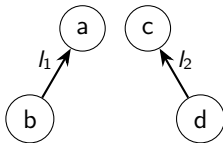
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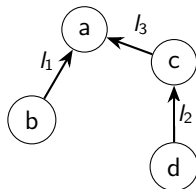
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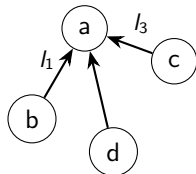
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`find(d) = a,`



## Definition

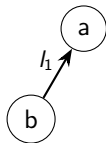
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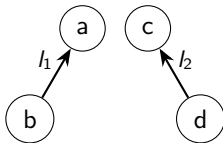
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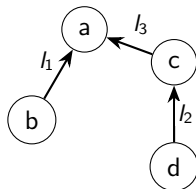
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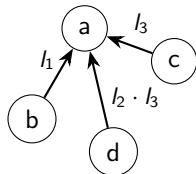
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$\text{find}(d) = a, l_2 \cdot l_3$



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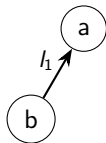
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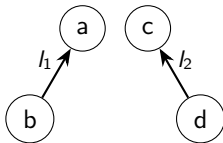
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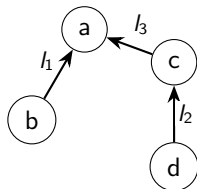
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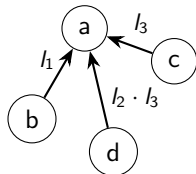
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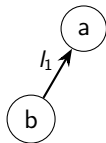
The labels have a **composition operation** that:

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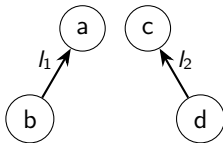
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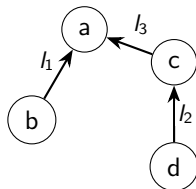
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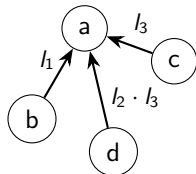
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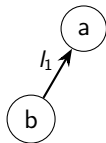
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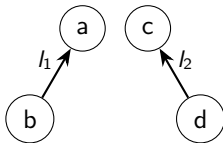
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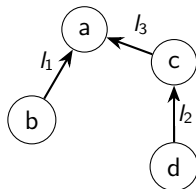
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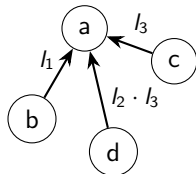
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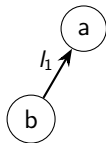
The labels have a **composition operation** that:

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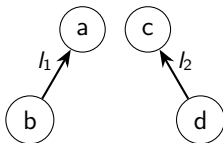
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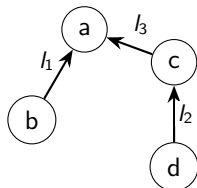
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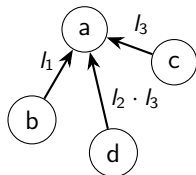
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## Definition

Labeled union-find is an extension of union-find in which the relation between elements is parametrized (labeled).

The labels have a **composition operation** that:

- ▶ Is invertible.
- ▶ Is associative.
- ▶ Has an identity element.

Forming a **group** with the labels.

## Equivalence modulo relocation II

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In the **labeled union-find** used to represent equivalence modulo relocation:

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- ▶ Nodes: n-sequences.

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- ▶ Labels: linear polynomials.



## Equivalence modulo relocation II

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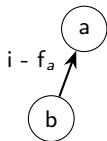
- ▶ Nodes: n-sequences.
- ▶ Labels: linear polynomials.
- ▶ Composition operation: integer addition.

## Equivalence modulo relocation II

In the **labeled union-find** used to represent equivalence modulo relocation:

- ▶ Nodes: n-sequences.
- ▶ Labels: linear polynomials.
- ▶ Composition operation: integer addition.

$b = \text{relocate}(a, i)$

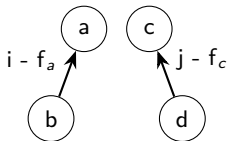
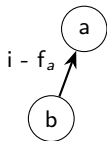


## Equivalence modulo relocation II

In the **labeled union-find** used to represent equivalence modulo relocation:

- ▶ Nodes: n-sequences.
- ▶ Labels: linear polynomials.
- ▶ Composition operation: integer addition.

$$b = \text{relocate}(a, i) \quad d = \text{relocate}(c, j)$$

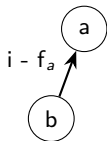


## Equivalence modulo relocation II

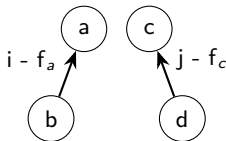
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- ▶ Labels: linear polynomials.
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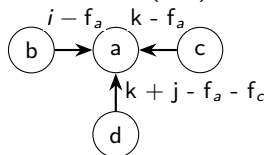
$b = \text{relocate}(a, i)$



$d = \text{relocate}(c, j)$



$c = \text{relocate}(a, k)$

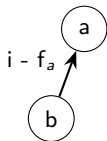


## Equivalence modulo relocation II

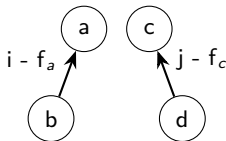
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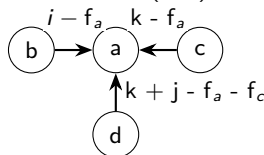
$b = \text{relocate}(a, i)$



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$c = \text{relocate}(a, k)$



In the implementation, it also holds a domain:

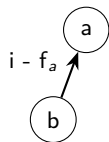
$$r \mapsto M : \left\{ \begin{array}{l} 0 \mapsto r \\ \delta_1 \mapsto s_1 \\ \dots \\ \delta_n \mapsto s_n \end{array} \right\}$$

# Equivalence modulo relocation II

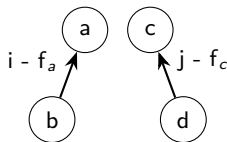
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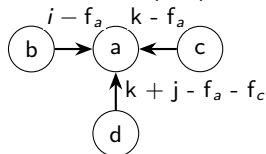
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In the implementation, it also holds a domain:

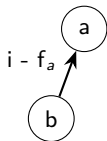
$$r \mapsto M : \left\{ \begin{array}{l} 0 \mapsto r \\ \delta_1 \mapsto s_1 \\ \dots \\ \delta_n \mapsto s_n \end{array} \right\} \cup \{\delta_i \mapsto s'_i\}$$

## Equivalence modulo relocation II

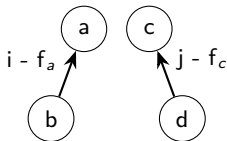
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- ▶ Nodes: n-sequences.
- ▶ Labels: linear polynomials.
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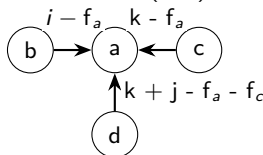
$b = \text{relocate}(a, i)$



$d = \text{relocate}(c, j)$



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In the implementation, it also holds a domain:

$$r \mapsto M : \left\{ \begin{array}{l} 0 \mapsto r \\ \delta_1 \mapsto s_1 \\ \dots \\ \delta_n \mapsto s_n \end{array} \right\} \cup \{\delta_i \mapsto s'_i\} \rightarrow \delta_i \in \text{Dom}(M) \implies s'_i = s_i$$

# Outline

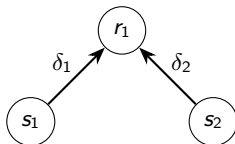
---

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  - **Constraint factorization**
  - Encoding sequences over n-Indexed Sequences
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5. Conclusion



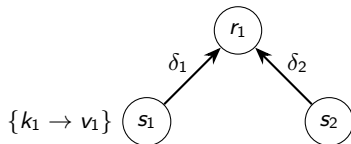
# Constraint factorization

---



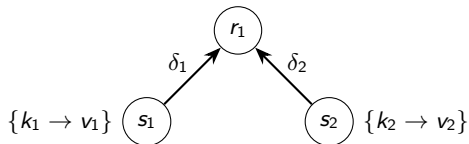
# Constraint factorization

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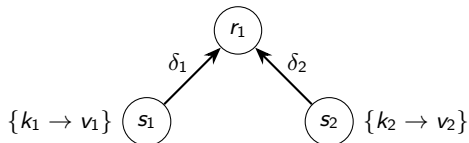


# Constraint factorization

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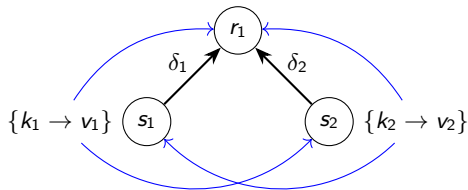


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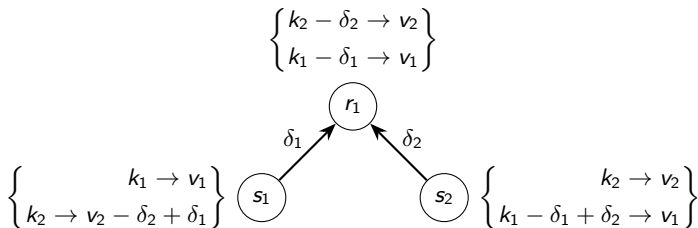
$$\text{Get-Reloc} \frac{v = \text{get}(s, i) \quad s =_{\text{reloc}} r}{i < f_s \vee l_s < i \quad || \quad f_s \leq i \leq l_s \wedge v = \text{get}(r, i - f_s + f_r)}$$

# Constraint factorization



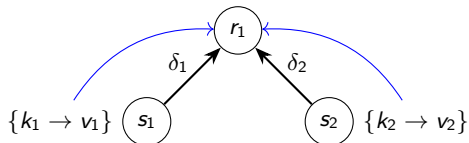
$$\text{Get-Reloc} \frac{v = \text{get}(s, i) \quad s =_{\text{reloc}} r}{i < f_s \vee l_s < i \quad || \quad f_s \leq i \leq l_s \wedge v = \text{get}(r, i - f_s + f_r)}$$

# Constraint factorization



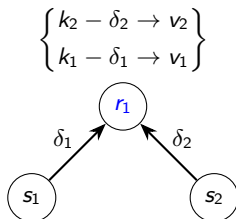
$$\text{Get-Reloc} \frac{v = \text{get}(s, i) \quad s =_{\text{reloc}} \textcolor{blue}{r}}{i < f_s \vee l_s < i \quad || \quad f_s \leq i \leq l_s \wedge v = \text{get}(\textcolor{blue}{r}, i - f_s + f_{\textcolor{blue}{r}})}$$

# Constraint factorization



$$\text{Get-Reloc} \frac{v = \text{get}(s, i) \quad s =_{\text{reloc}} \textcolor{blue}{r}}{i < f_s \vee l_s < i \quad || \quad f_s \leq i \leq l_s \wedge v = \text{get}(\textcolor{blue}{r}, i - f_s + f_r)}$$

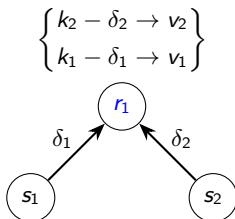
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# Constraint factorization



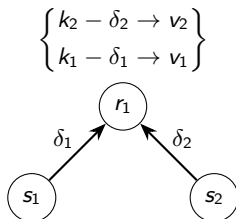
$$\text{Get-Reloc} \frac{v = \text{get}(s, i) \quad s =_{\text{reloc}} r}{i < f_s \vee l_s < i \quad || \quad f_s \leq i \leq l_s \wedge v = \text{get}(r, i - f_s + f_r)}$$

Also applies to NS-Comp-Reloc:

$$\text{NS-Comp-Reloc} \frac{s = k_1 :: k_2 :: \dots :: k_n \quad s =_{\text{reloc}} r}{\begin{array}{l} r = \text{relocate}(k_1, f_r) :: \\ \text{relocate}(k_2, f_{k_2} - f_s + f_r) :: \dots :: \\ \text{relocate}(k_n, f_{k_n} - f_s + f_r) \end{array}}$$

# Constraint factorization

---



To read more on how it is used in arithmetic reasoning:

► **"Relational Abstractions Based on Labeled Union-Find"**

Dorian Lesbre, Matthieu Lemerre, Hichem Rami Ait-El-Hara, and François Bobot. [PLDI 2025](#)

# Outline

---

1. The SMT theory of n-Indexed Sequences
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# Encoding sequences over n-Indexed Sequences

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- ▶  $\text{seq.empty}$ : Represented by a special constant symbol  $\epsilon$ , an empty  $n$ -sequence with  $f_\epsilon = 0$  and  $l_\epsilon = -1$ .
- ▶  $\text{seq.}++(s_1, s_2, s_3, \dots, s_n)$ :

$\text{let}(c_1, \text{concat}(s_1, \text{relocate}(s_2, l_{s_1} + 1)),$   
 $\text{let}(c_2, \text{concat}(c_1, \text{relocate}(s_3, l_{c_1} + 1)),$   
 $\dots$   
 $\text{concat}(c_{n-2}, \text{relocate}(s_n, l_{c_{n-2}} + 1))))$

# Outline

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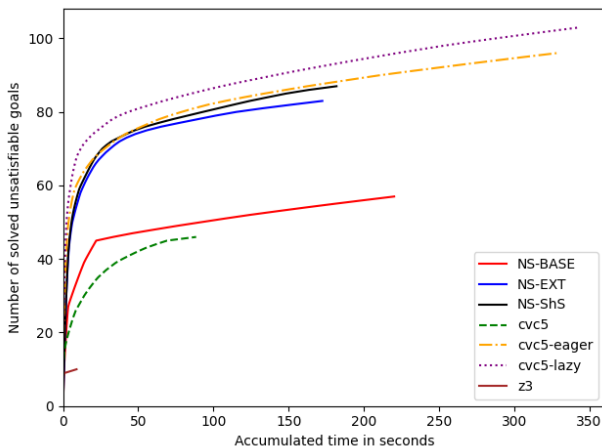


## Experimental evaluation: context

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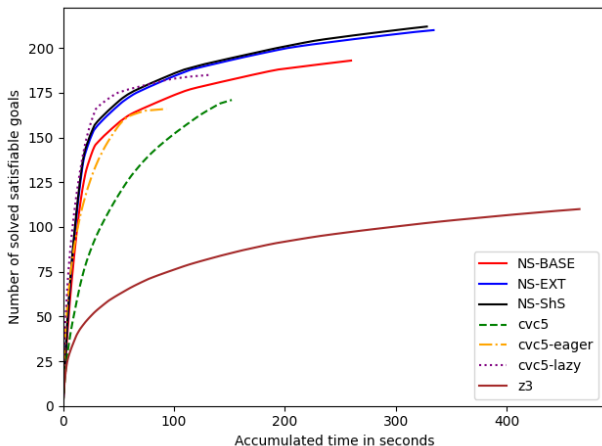
- ▶ The experimentation was done on quantifier free sequence and n-sequence benchmarks, containing only sequence and n-sequence operations.
- ▶ The experimentation compares implementations of NS-BASE, NS-EXT and NS-ShS in Colibri2 with:
  - ▶ Sequence support in cvc5 and Z3.
  - ▶ Support for n-sequences encoded with ADTs and Sequences in cvc5 and Z3.

# Experimental evaluation: UNSAT Seq



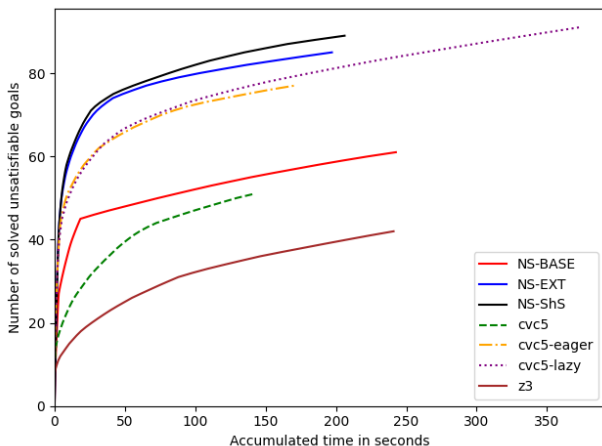
**Figure:** Number of solved goals by accumulated time (in seconds) on unsatisfiable quantifier-free Sequence benchmarks.

# Experimental evaluation: SAT Seq



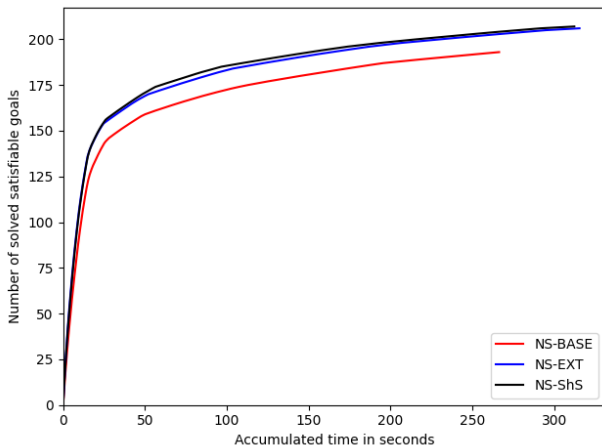
**Figure:** Number of solved goals by accumulated time (in seconds) on satisfiable quantifier-free Sequence benchmarks.

# Experimental evaluation: UNSAT NSeq



**Figure:** Number of solved goals by accumulated time (in seconds) on unsatisfiable quantifier-free  $n$ -Indexed Sequence benchmarks.

# Experimental evaluation: SAT NSeq



**Figure:** Number of solved goals by accumulated time (in seconds) on satisfiable quantifier-free  $n$ -Indexed Sequence benchmarks.

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Contributions presented in this talk:

- ▶ The theory of  $n$ -Indexed Sequences.
- ▶ Various ways to reason over it.
- ▶ Experimental evaluation.



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Additional contributions in the manuscript:

- ▶ Soundness proofs.
- ▶ Implementation details and formalizations.
- ▶ Work on real and integer arithmetic reasoning.  
(Labeled union-find for intervals and difference logic)

# Conclusion

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Future work:

- ▶ Acquire more benchmarks
- ▶ Add ( $n$ -)sequences to Alt-Ergo
- ▶ Improve reasoning over  $n$ -sequences with quantifiers.

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Contributions to software:

- ▶ Colibri2
- ▶ Alt-Ergo
- ▶ Smtml
- ▶ Dolmen
- ▶ SMT LSP

# Conclusion

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Contributions presented in this talk:

- ▶ The theory of  $n$ -Indexed Sequences.
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Additional contributions in the manuscript:

- ▶ Soundness proofs.
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Future work:

- ▶ Acquire more benchmarks
- ▶ Add ( $n$ -)sequences to Alt-Ergo
- ▶ Improve reasoning over  $n$ -sequences with quantifiers.

Other:

- ▶ Co-supervised an intern for 6 months (Félix Loyau-Kahn, Master's student) on using AI for SMT solver selection.

Contributions to software:

- ▶ Colibri2
- ▶ Alt-Ergo
- ▶ Smtml
- ▶ Dolmen
- ▶ SMT LSP

# Publications

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- ▶ **"On SMT Theory Design: The Case of Sequences"**  
Hichem Rami Ait-El-Hara, François Bobot and Guillaume Bury. [LPAR 2024](#)
- ▶ **"An SMT Theory for n-Indexed Sequences"**  
Hichem Rami Ait-El-Hara, François Bobot, and Guillaume Bury. [SMT 2024](#)
- ▶ **"Reasoning over n-indexed sequences in SMT"**  
Hichem Rami Ait-El-Hara, François Bobot, and Guillaume Bury. [Acta Informatica 62.3 \(Aug. 2025\)](#)
- ▶ **"Relational Abstractions Based on Labeled Union-Find"**  
Dorian Lesbre, Matthieu Lemerre, Hichem Rami Ait-El-Hara, and François Bobot. [PLDI 2025](#)
- ▶ **"Constraint Propagation for Bit-Vectors in Alt-Ergo"**  
Hichem Rami Ait-El-Hara, Guillaume Bury, Basile Clément, and Pierre Villemot. [SMT 2025](#)

Preprints:

- ▶ **"Smt.ml: A Multi-Backend Frontend for SMT Solvers in OCaml"**  
João Madeira Pereira, Filipe Marques, Pedro Adão, Hichem Rami Ait-El-Hara, Léo Andrès, Arthur Carcano, Pierre Chambart, Nuno Santos, and José Frago Santos. [To be submitted to TACAS 2026.](#)

# Appendix 1: bibliography I

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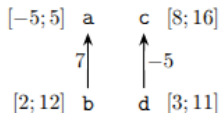
- [Bjø+12] N Bjørner et al. “An SMT-LIB Format for Sequences and Regular Expressions”. In: *Strings* (Jan. 2012).
- [CH15] Jürgen Christ and Jochen Hoenicke. “Weakly Equivalent Arrays”. In: *Frontiers of Combining Systems*. Ed. by Carsten Lutz and Silvio Ranise. Cham: Springer International Publishing, 2015, pp. 119–134. ISBN: 978-3-319-24246-0. DOI: 10.1007/978-3-319-24246-0\_8.
- [MB09] Leonardo Mendonça de Moura and Nikolaj S. Bjørner. “Generalized, efficient array decision procedures”. In: *Proceedings of 9th International Conference on Formal Methods in Computer-Aided Design, FMCAD 2009, 15-18 November 2009, Austin, Texas, USA*. IEEE, 2009, pp. 45–52. DOI: 10.1109/FMCAD.2009.5351142.
- [McC62] John McCarthy. “Towards a Mathematical Science of Computation”. In: *Information Processing, Proceedings of the 2nd IFIP Congress 1962, Munich, Germany, August 27 - September 1, 1962*. North-Holland, 1962, pp. 21–28.
- [She+23] Ying Sheng et al. “Reasoning About Vectors: Satisfiability Modulo a Theory of Sequences”. In: *Journal of Automated Reasoning* 67.3 (Sept. 2023), p. 32. ISSN: 1573-0670. DOI: 10.1007/s10817-023-09682-2.

6. Labeled Union-Find for Arithmetic reasoning

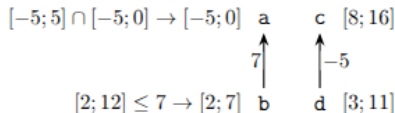
7. NS-BASE and NS-EXT

# Reduced Product

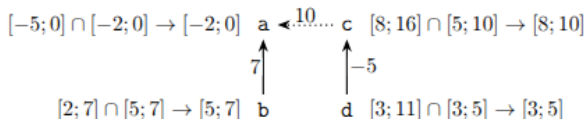
0. `init:`



1. `assert ( $b \leq 7$ ):`



2. `repr_change_hook(c, 10, b):`



3. `end:`

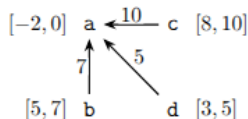
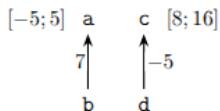


Figure 6.4: Example of the usage of the constant difference relation for constraint propagation over the domain of intervals.

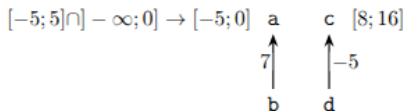


# Group Action

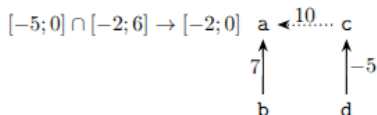
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2. `repr_change_hookAr(c, 10, b):`



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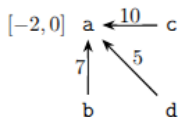


Figure 6.5: Example of the usage of the constant difference relation for constraint factorization over the domain of intervals.

# Normal forms

## Definition (NSeq term normal form)

For simplicity, we introduce the concatenation operator  $::$  with the invariant:

$$s \mapsto s_1 :: s_2 \implies f_s = f_{s_1} \wedge l_s = l_{s_2} \wedge f_{s_2} = l_{s_1} + 1$$

## Normalization

The following rewriting rules are applied whenever possible:

$$\left\{ \begin{array}{l} s \mapsto [w_1 ::]x[:: w_2] \\ x \mapsto y :: z \end{array} \right\} \longrightarrow \left\{ \begin{array}{l} s \mapsto [w_1 ::]y :: z[:: w_2] \\ x \mapsto y :: z \end{array} \right.$$

And if  $l_y < f_y$  is deduced:

$$\left\{ \begin{array}{l} s \mapsto [w_1 ::]y :: z[:: w_2] \\ x \mapsto y :: z \end{array} \right\} \longrightarrow \left\{ \begin{array}{l} s \mapsto [w_1 ::]z[:: w_2] \\ x \mapsto z \end{array} \right.$$